An Improved Parameterized Algorithm for Treewidth

Tuukka Korhonen



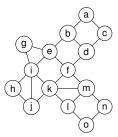
UNIVERSITY OF BERGEN

joint work with Daniel Lokshtanov¹

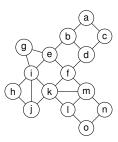
¹University of California Santa Barbara

UCSB CS Theory Colloquium

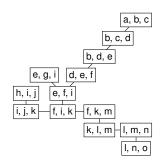
9 November 2022



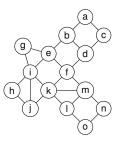
Graph G



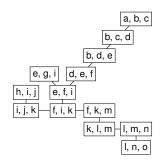
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A tree decomposition of G

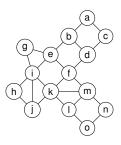


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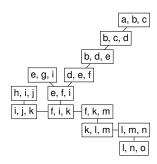


A tree decomposition of G

1. Every vertex should be in a bag

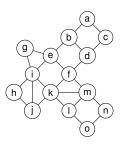


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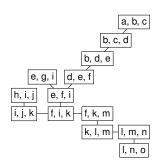


A tree decomposition of G

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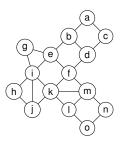


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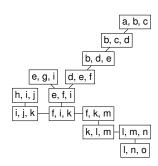


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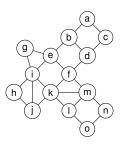


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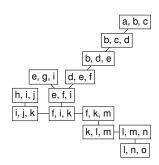


A tree decomposition of G

- 1. Every vertex should be in a bag
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- 4. Width = maximum bag size -1

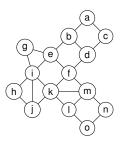


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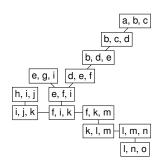


A tree decomposition of GWidth = 2

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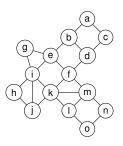


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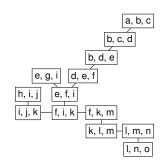


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- 5. Treewidth of G = minimum width of tree decomposition of G

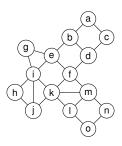


Graph *G* Treewidth 2

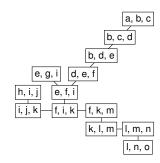


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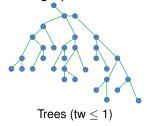
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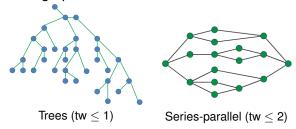


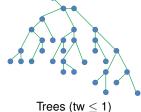
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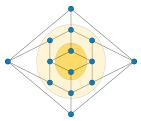
[Bertele & Brioschi'72, Halin'76, Robertson & Seymour'84]







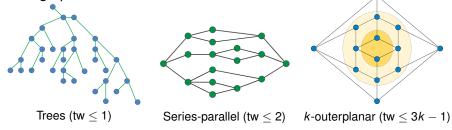




 $(tw \le 1) Series-parallel (tw \le 2)$

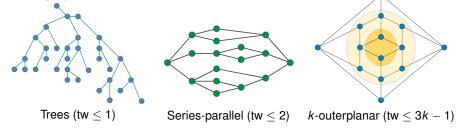
k-outerplanar (tw $\leq 3k-1$)

Some graphs of small treewidth:

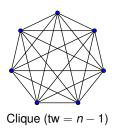


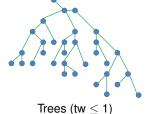
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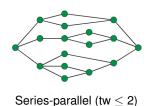
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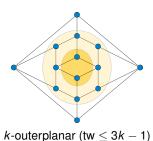


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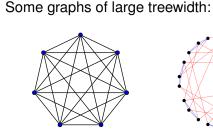


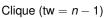






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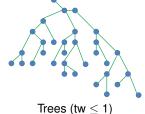


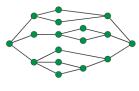


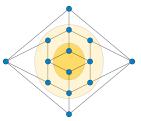


Expanders (tw = $\Theta(n)$)

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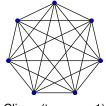


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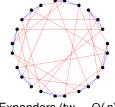
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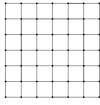
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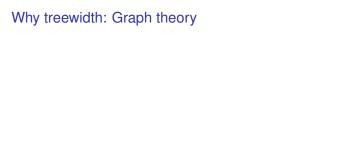
Clique (tw = n - 1)



Expanders (tw = $\Theta(n)$)

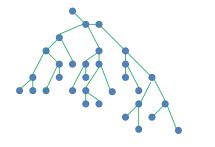


 $n \times n$ -grid (tw = n)

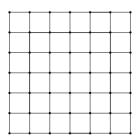


Why treewidth: Graph theory

Dichotomy: Either small treewidth, or large grid inside

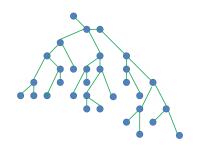


or

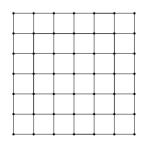


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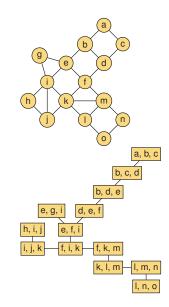


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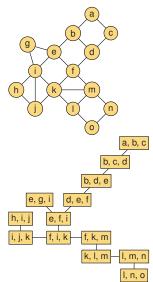


Grid minor theorem (Robertson & Seymour'86)

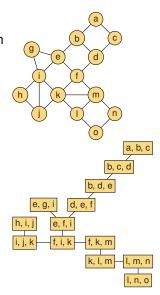
Exists function f(k) s.t. any graph with tw $\geq f(k)$ has a $k \times k$ -grid minor.



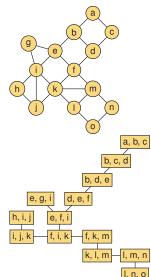
 Algorithms on trees generalize to algorithms on graphs of small treewidth



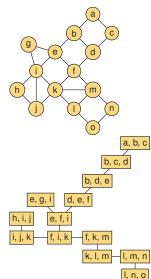
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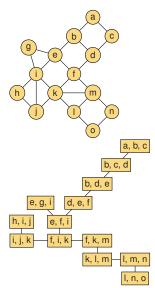
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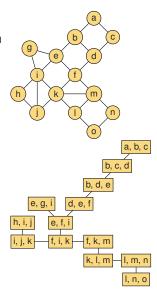
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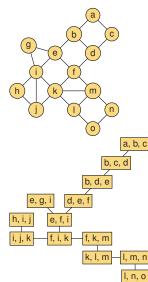
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- Need to compute the tree decomposition first!





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Computing treewidth (and the tree decomposition)

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Theorem (This work)

There is a $2^{\mathcal{O}(k^2)}n^4$ time algorithm for treewidth.

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Theorem (This work)

There is a $k^{\mathcal{O}(k/\varepsilon)}n^4$ time $(1+\varepsilon)$ -approximation algorithm for treewidth.

Outline

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1. How to improve a tree decomposition

Suffices to solve the Subset treewidth problem

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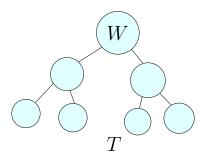
2. Solving the subset treewidth problem

Algorithms for subset treewidth that then imply algorithms for treewidth

1. How to improve a tree decomposition

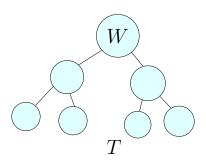
How to improve a tree decomposition

Suppose we have a tree decomposition T whose largest bag is W



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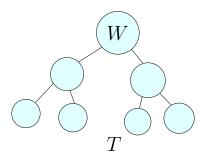
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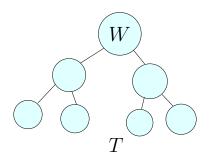
1. either decrease the number of bags of size |W| while not increasing the width of T, or



Suppose we have a tree decomposition \mathcal{T} whose largest bag is \mathcal{W}

Goal:

- 1. either decrease the number of bags of size |W| while not increasing the width of T, or
- 2. conclude that T is (approximately) optimal

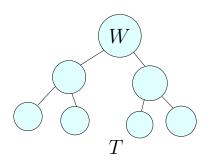


Suppose we have a tree decomposition T whose largest bag is W

Goal:

- 1. either decrease the number of bags of size |W| while not increasing the width of T, or
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Repeat for $\mathcal{O}(\mathsf{tw}(G) \cdot n)$ iterations to get an (approximately) optimal tree decomposition



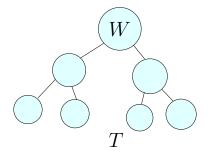
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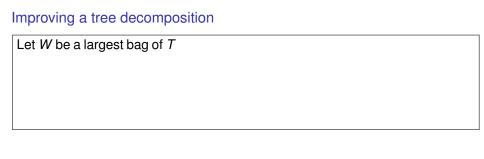
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Repeat for $\mathcal{O}(\mathsf{tw}(G) \cdot n)$ iterations to get an (approximately) optimal tree decomposition

(assume to start with width $\mathcal{O}(\mathsf{tw}(G))$ decomposition)





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SUBSET TREEWIDTH

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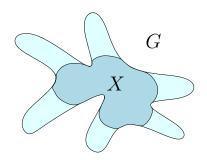
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Torso?



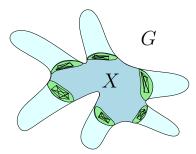
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Torso?



• Make neighborhoods of components of $G \setminus X$ into cliques

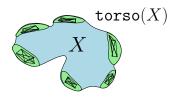
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Torso?



- Make neighborhoods of components of $G \setminus X$ into cliques
- Delete V(G) \ X

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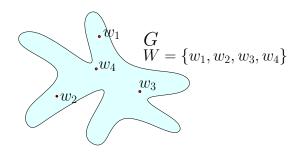
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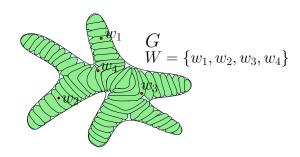
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Observations:

• If T is not optimal, then such X exists by taking X = V(G)



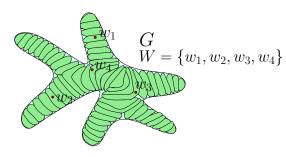
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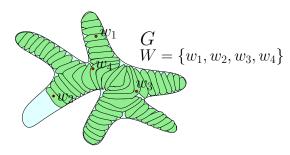
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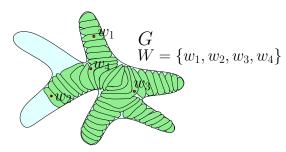
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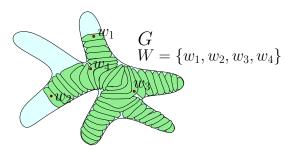
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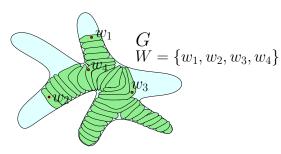
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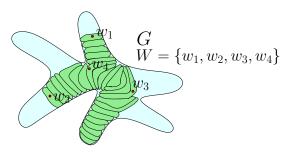
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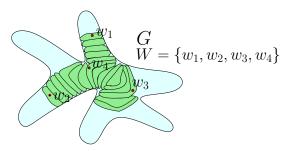
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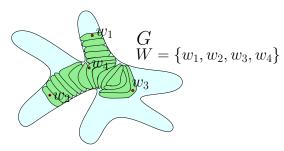
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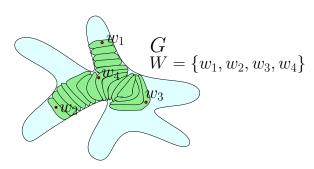
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Big-leaf formulation:



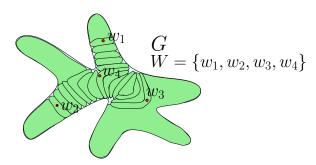
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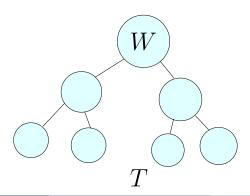
• Find a tree decomposition of G whose internal bags have size $\leq |W| - 1$ and cover W, but leaf bags can be arbitrarily large



SUBSET TREEWIDTH

Have:

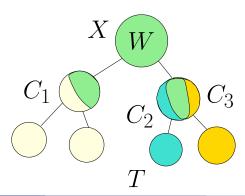
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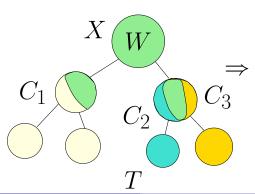
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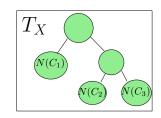


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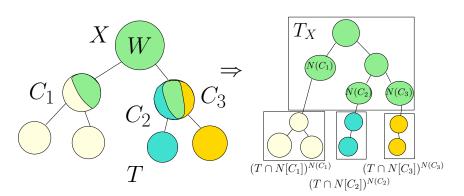


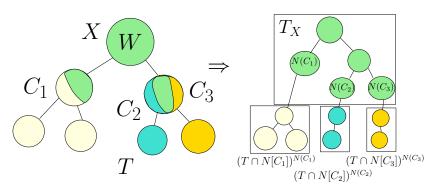


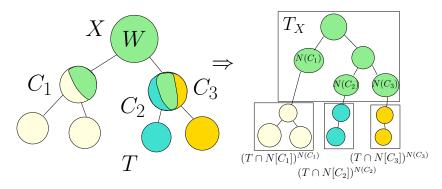
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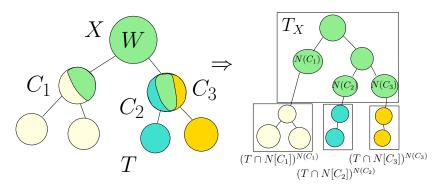
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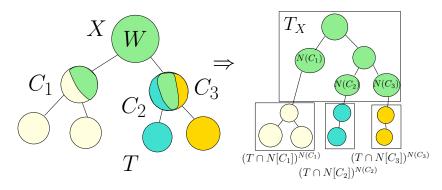




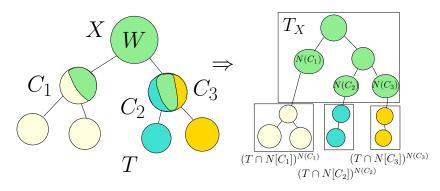
• Want: The copy of a bag in $(T \cap N[C_i])^{N(C_i)}$ is not larger than the original bag



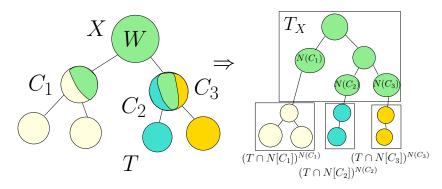
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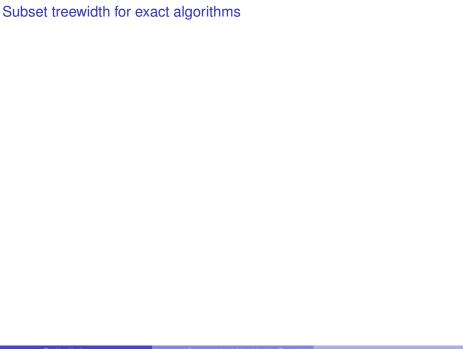
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- Proofs by Bellenbaum-Diestel type arguments
- (actually need a bit stronger condition than linkedness for improvement)



SUBSET TREEWIDTH

Input: Graph *G*, integer *k*, set of vertices $W \subseteq V(G)$ with |W| = k + 2

Output: Set $X \subseteq V(G)$ with $W \subseteq X$ and tree decomposition of torso(X) of width $\leq k$ or that the treewidth of G is > k

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Theorem

If there is an $f(k) \cdot n^{\mathcal{O}(1)}$ time algorithm for subset treewidth, then there is an $f(k) \cdot n^{\mathcal{O}(1)}$ time algorithm for treewidth with the same function f.

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 $2^{\mathcal{O}(k^2)} \textit{n}^2 \text{ time algorithm for subset treewidth} \rightarrow 2^{\mathcal{O}(k^2)} \textit{n}^4 \text{ time algorithm for treewidth}$



PARTITIONED SUBSET TREEWIDTH

Input: Graph G, integer k, set of vertices $W \subseteq V(G)$ with |W| = k+2 that is partitioned into t cliques W_1, \ldots, W_t

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 $k^{\mathcal{O}(kt)}n^2$ time algorithm for partitioned subset treewidth $\to k^{\mathcal{O}(k/\varepsilon)}n^4$ time $(1+\varepsilon)$ -approximation algorithm for treewidth

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ullet Idea: Can afford to increase treewidth by εk

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 $k^{\mathcal{O}(kt)}n^2$ time algorithm for partitioned subset treewidth $\to k^{\mathcal{O}(k/\varepsilon)}n^4$ time $(1+\varepsilon)$ -approximation algorithm for treewidth

- Idea: Can afford to increase treewidth by εk
- Any set W can be partitioned into $t = \mathcal{O}(1/\varepsilon)$ sets W_1, \ldots, W_t so that making them into cliques increases treewidth by at most $\varepsilon |W|$

2. Solving the subset treewidth problem

Solving the subset treewidth problem



Solving the subset treewidth problem

Goal: Sketch $k^{\mathcal{O}(kt)} n^{\mathcal{O}(1)}$ time algorithm for partitioned subset treewidth

2. Solving the subset treewidth problem

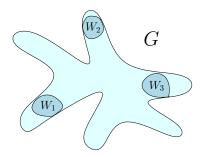
Solving the subset treewidth problem

Goal: Sketch $k^{\mathcal{O}(kt)} n^{\mathcal{O}(1)}$ time algorithm for partitioned subset treewidth

(this is also a $k^{\mathcal{O}(k^2)} n^{\mathcal{O}(1)}$ time algorithm for subset treewidth)

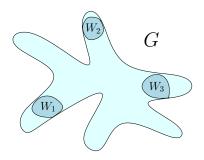
Setting:

• Input: Graph G, t terminal cliques W_1, \ldots, W_t , and an integer k



Setting:

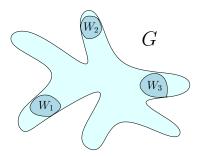
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Reduction rule:

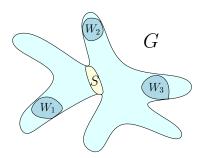


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Reduction rule:

Let S be a non-trivial minimum size (W_i, W_j) -separator

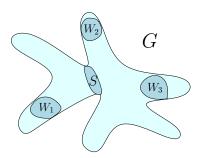


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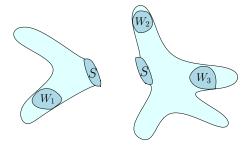
Solving subset treewidth

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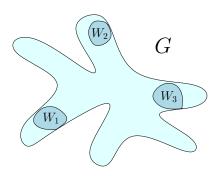
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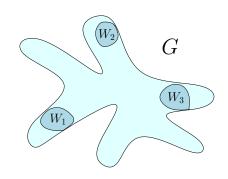
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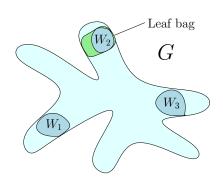
Now terminal cliques strongly linked into each other



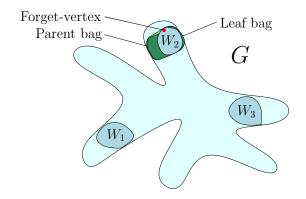
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- Goal: To make progress, increase the size/flow of some terminal clique



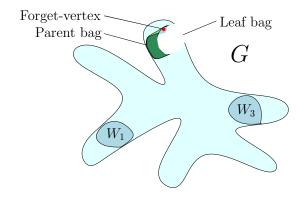
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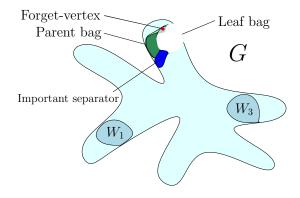
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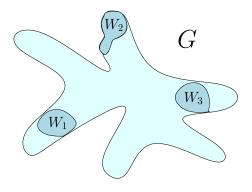
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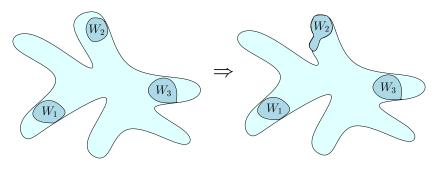
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- Increase W₂ by guessing an important separator



- Now terminal cliques strongly linked into each other
- Goal: To make progress, increase the size/flow of some terminal clique
- Increase W₂ by guessing an important separator

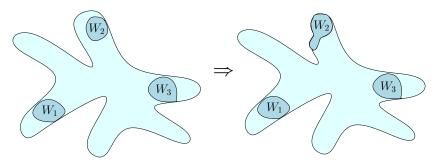


Analysis of branching



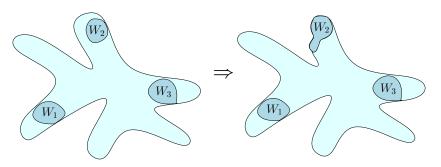
 Increased the size/flow of a leaf terminal clique by guessing a forget-vertex and an important separator

Analysis of branching



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Analysis of branching



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- To get $k^{\mathcal{O}(kt)} n^{\mathcal{O}(1)}$ time, need also an important separator hitting set lemma

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- How much can the n⁴ factor be optimized?

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