

# Linear-Time Algorithms for $k$ -Edge-Connected Components, $k$ -Lean Tree Decompositions, and More

Tuukka Korhonen



STOC 2025

23 June 2025

## Graph connectivity problems

Almost-linear-time algorithms for many problems:

- Edge connectivity (global edge min-cut),  $\mathcal{O}(m \log^3 n)$  [Karger '96]
- Vertex connectivity (global vertex min-cut),  $\mathcal{O}(m^{1+o(1)})$  [Li, Nanongkai, Panigrahi, Saranurak & Yingchareonthawornchai '21]
- Gomory-Hu tree,  $\mathcal{O}(m^{1+o(1)})$  [Abboud, Li, Panigrahi & Saranurak '23]

## Graph connectivity problems

Almost-linear-time algorithms for many problems:

- Edge connectivity (global edge min-cut),  $\mathcal{O}(m \log^3 n)$  [Karger '96]
- Vertex connectivity (global vertex min-cut),  $\mathcal{O}(m^{1+o(1)})$  [Li, Nanongkai, Panigrahi, Saranurak & Yingchareonthawornchai '21]
- Gomory-Hu tree,  $\mathcal{O}(m^{1+o(1)})$  [Abboud, Li, Panigrahi & Saranurak '23]

No idea about truly linear-time!

## Graph connectivity problems

Almost-linear-time algorithms for many problems:

- Edge connectivity (global edge min-cut),  $\mathcal{O}(m \log^3 n)$  [Karger '96]
- Vertex connectivity (global vertex min-cut),  $\mathcal{O}(m^{1+o(1)})$  [Li, Nanongkai, Panigrahi, Saranurak & Yingchareonthawornchai '21]
- Gomory-Hu tree,  $\mathcal{O}(m^{1+o(1)})$  [Abboud, Li, Panigrahi & Saranurak '23]

No idea about truly linear-time!

This work

$f(k) \cdot m$  time algorithms for connectivity problems restricted to cuts/separators of size  $< k$

## Graph connectivity problems

Almost-linear-time algorithms for many problems:

- Edge connectivity (global edge min-cut),  $\mathcal{O}(m \log^3 n)$  [Karger '96]
- Vertex connectivity (global vertex min-cut),  $\mathcal{O}(m^{1+o(1)})$  [Li, Nanongkai, Panigrahi, Saranurak & Yingchareonthawornchai '21]
- Gomory-Hu tree,  $\mathcal{O}(m^{1+o(1)})$  [Abboud, Li, Panigrahi & Saranurak '23]

No idea about truly linear-time!

### This work

$f(k) \cdot m$  time algorithms for connectivity problems restricted to cuts/separators of size  $< k$

- Deterministic!

## Graph connectivity problems

Almost-linear-time algorithms for many problems:

- Edge connectivity (global edge min-cut),  $\mathcal{O}(m \log^3 n)$  [Karger '96]
- Vertex connectivity (global vertex min-cut),  $\mathcal{O}(m^{1+o(1)})$  [Li, Nanongkai, Panigrahi, Saranurak & Yingchareonthawornchai '21]
- Gomory-Hu tree,  $\mathcal{O}(m^{1+o(1)})$  [Abboud, Li, Panigrahi & Saranurak '23]

No idea about truly linear-time!

### This work

$f(k) \cdot m$  time algorithms for connectivity problems restricted to cuts/separators of size  $< k$

- Deterministic!
- One graph decomposition to rule them all!

# $k$ -Edge-Connected Components

## $k$ -Edge-Connected Components

**Def:** Vertices  $u$  and  $v$  in the same  $k$ -edge-connected component if no  $(u, v)$ -cut with  $< k$  edges



## $k$ -Edge-Connected Components

**Def:** Vertices  $u$  and  $v$  in the same  $k$ -edge-connected component if no  $(u, v)$ -cut with  $< k$  edges

**Obs:** This gives an equivalence relation among vertices  $\Rightarrow$  unique partition into components

## $k$ -Edge-Connected Components

**Def:** Vertices  $u$  and  $v$  in the same  $k$ -edge-connected component if no  $(u, v)$ -cut with  $< k$  edges

**Obs:** This gives an equivalence relation among vertices  $\Rightarrow$  unique partition into components

### Theorem (This work)

There is a  $k^{\mathcal{O}(k^2)}m$  time algorithm for  $k$ -edge-connected components

## $k$ -Edge-Connected Components

**Def:** Vertices  $u$  and  $v$  in the same  $k$ -edge-connected component if no  $(u, v)$ -cut with  $< k$  edges

**Obs:** This gives an equivalence relation among vertices  $\Rightarrow$  unique partition into components

### Theorem (This work)

There is a  $k^{\mathcal{O}(k^2)}m$  time algorithm for  $k$ -edge-connected components

Previous results:

- $\mathcal{O}(m)$  for  $k = 2$  [Tarjan '72]
- $\mathcal{O}(m)$  for  $k = 3$  [Galil & Italiano '91] (using [Hopcroft & Tarjan '73])
- $\mathcal{O}(m)$  for  $k = 4$  [Nadara, Radecki, Smulewicz & Sokołowski '21, Georgiadis, Italiano & Kosinas '21]
- $\mathcal{O}(m)$  for  $k = 5$  [Kosinas '24]

## $k$ -Edge-Connected Components

**Def:** Vertices  $u$  and  $v$  in the same  $k$ -edge-connected component if no  $(u, v)$ -cut with  $< k$  edges

**Obs:** This gives an equivalence relation among vertices  $\Rightarrow$  unique partition into components

### Theorem (This work)

There is a  $k^{\mathcal{O}(k^2)}m$  time algorithm for  $k$ -edge-connected components

Previous results:

- $\mathcal{O}(m)$  for  $k = 2$  [Tarjan '72]
- $\mathcal{O}(m)$  for  $k = 3$  [Galil & Italiano '91] (using [Hopcroft & Tarjan '73])
- $\mathcal{O}(m)$  for  $k = 4$  [Nadara, Radecki, Smulewicz & Sokołowski '21, Georgiadis, Italiano & Kosinas '21]
- $\mathcal{O}(m)$  for  $k = 5$  [Kosinas '24]
- $\text{poly}(k) \cdot m \text{ polylog } m$  for all  $k$  [Hariharan, Kavitha & Panigrahi '07]
- $m^{1+o(1)}$  for all  $k$  [Abboud, Li, Panigrahi & Saranurak '23]

## $k$ -Edge-Connected Components

**Def:** Vertices  $u$  and  $v$  in the same  $k$ -edge-connected component if no  $(u, v)$ -cut with  $< k$  edges

**Obs:** This gives an equivalence relation among vertices  $\Rightarrow$  unique partition into components

### Theorem (This work)

There is a  $k^{\mathcal{O}(k^2)}m$  time algorithm for  $k$ -edge-connected components

Previous results:

- $\mathcal{O}(m)$  for  $k = 2$  [Tarjan '72]
- $\mathcal{O}(m)$  for  $k = 3$  [Galil & Italiano '91] (using [Hopcroft & Tarjan '73])
- $\mathcal{O}(m)$  for  $k = 4$  [Nadara, Radecki, Smulewicz & Sokołowski '21, Georgiadis, Italiano & Kosinas '21]
- $\mathcal{O}(m)$  for  $k = 5$  [Kosinas '24]
- $\text{poly}(k) \cdot m \text{ polylog } m$  for all  $k$  [Hariharan, Kavitha & Panigrahi '07]
- $m^{1+o(1)}$  for all  $k$  [Abboud, Li, Panigrahi & Saranurak '23]

For minimum cut:

- $\mathcal{O}(k^2 m \log m)$  [Gabow '91],  $\mathcal{O}(m \text{ polylog } m)$  [Karger '96]

## $k$ -Lean Tree Decompositions and More

Main technical result:

Theorem (This work)

There is a  $k^{\mathcal{O}(k^2)}m$  time algorithm for computing a “ $k$ -lean tree decomposition” of a given graph.

## $k$ -Lean Tree Decompositions and More

Main technical result:

Theorem (This work)

There is a  $k^{\mathcal{O}(k^2)}m$  time algorithm for computing a “ $k$ -lean tree decomposition” of a given graph.

Implies the first “parameterized linear-time” ( $f(k) \cdot m$  time) algorithms for many problems:

## $k$ -Lean Tree Decompositions and More

Main technical result:

### Theorem (This work)

There is a  $k^{\mathcal{O}(k^2)}m$  time algorithm for computing a “ $k$ -lean tree decomposition” of a given graph.

Implies the first “parameterized linear-time” ( $f(k) \cdot m$  time) algorithms for many problems:

- $k$ -Gomory-Hu tree in  $k^{\mathcal{O}(k^2)}m$  time
  - ▶ Previously  $\text{poly}(k) \cdot m \text{ polylog } m$  [Hariharan, Kavitha, Panigrahi '07]



## $k$ -Lean Tree Decompositions and More

Main technical result:

### Theorem (This work)

There is a  $k^{\mathcal{O}(k^2)}m$  time algorithm for computing a “ $k$ -lean tree decomposition” of a given graph.

Implies the first “parameterized linear-time” ( $f(k) \cdot m$  time) algorithms for many problems:

- $k$ -Gomory-Hu tree in  $k^{\mathcal{O}(k^2)}m$  time
  - ▶ Previously  $\text{poly}(k) \cdot m \text{ polylog } m$  [Hariharan, Kavitha, Panigrahi '07]
- $k$ -Vertex connectivity in  $k^{\mathcal{O}(k^2)}m$  time
  - ▶ Previously  $\mathcal{O}(k^3m \text{ polylog } m)$  [Forster, Nanongkai, Yang, Saranurak, Yingchareonthawornchai '20]

## $k$ -Lean Tree Decompositions and More

Main technical result:

### Theorem (This work)

There is a  $k^{\mathcal{O}(k^2)}m$  time algorithm for computing a “ $k$ -lean tree decomposition” of a given graph.

Implies the first “parameterized linear-time” ( $f(k) \cdot m$  time) algorithms for many problems:

- $k$ -Gomory-Hu tree in  $k^{\mathcal{O}(k^2)}m$  time
  - ▶ Previously  $\text{poly}(k) \cdot m \text{ polylog } m$  [Hariharan, Kavitha, Panigrahi '07]
- $k$ -Vertex connectivity in  $k^{\mathcal{O}(k^2)}m$  time
  - ▶ Previously  $\mathcal{O}(k^3 m \text{ polylog } m)$  [Forster, Nanongkai, Yang, Saranurak, Yingchareonthawornchai '20]
- Element connectivity  $k$ -Gomory-Hu tree in  $k^{\mathcal{O}(k^2)}m$  time
  - ▶ Previously  $k \cdot m^{1+o(1)}$  [Pettie, Saranurak, Yin '22]

## $k$ -Lean Tree Decompositions and More

Main technical result:

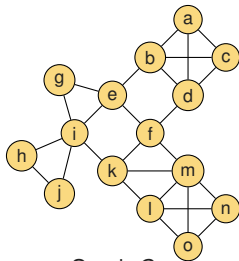
### Theorem (This work)

There is a  $k^{\mathcal{O}(k^2)}m$  time algorithm for computing a “ $k$ -lean tree decomposition” of a given graph.

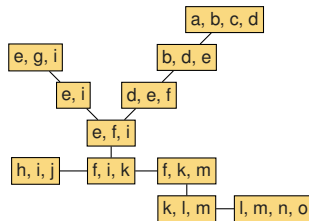
Implies the first “parameterized linear-time” ( $f(k) \cdot m$  time) algorithms for many problems:

- $k$ -Gomory-Hu tree in  $k^{\mathcal{O}(k^2)}m$  time
  - ▶ Previously  $\text{poly}(k) \cdot m \text{ polylog } m$  [Hariharan, Kavitha, Panigrahi '07]
- $k$ -Vertex connectivity in  $k^{\mathcal{O}(k^2)}m$  time
  - ▶ Previously  $\mathcal{O}(k^3 m \text{ polylog } m)$  [Forster, Nanongkai, Yang, Saranurak, Yingchareonthawornchai '20]
- Element connectivity  $k$ -Gomory-Hu tree in  $k^{\mathcal{O}(k^2)}m$  time
  - ▶ Previously  $k \cdot m^{1+o(1)}$  [Pettie, Saranurak, Yin '22]
- $k$ -Unbreakable tree decomposition in  $k^{\mathcal{O}(k^2)}m$  time (with optimal unbreakability parameters)
  - ▶ Previously  $k^{\mathcal{O}(k)}n^{\mathcal{O}(1)}$  [Cygan, Komosa, Lokshtanov, Pilipczuk, Pilipczuk, Saurabh, Wahlström '21]
  - ▶ and  $k^{\mathcal{O}(k)}m^{1+o(1)}$  [Anand, Lee, Li, Long, Saranurak '25] (suboptimal unbreakability parameters)

## $k$ -Lean Tree Decompositions

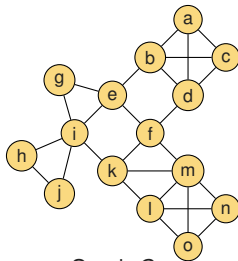


Graph G

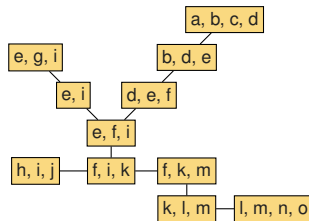


A 3-lean tree decomposition of G

## $k$ -Lean Tree Decompositions



Graph  $G$

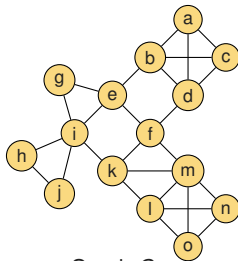


A 3-lean tree decomposition of  $G$

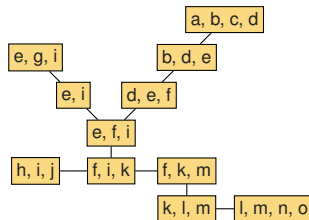
- Tree decomposition:

1. All vertices and edges are covered by bags
2. For each vertex  $v$ , the bags containing  $v$  form a connected subtree

## $k$ -Lean Tree Decompositions



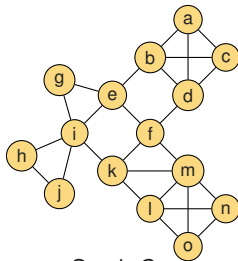
Graph  $G$



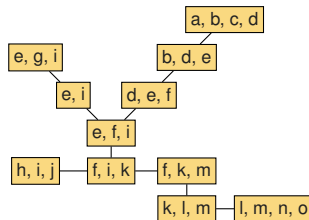
A 3-lean tree decomposition of  $G$

- Tree decomposition:
  1. All vertices and edges are covered by bags
  2. For each vertex  $v$ , the bags containing  $v$  form a connected subtree
- $k$ -lean:

## $k$ -Lean Tree Decompositions



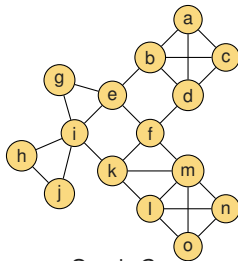
Graph  $G$



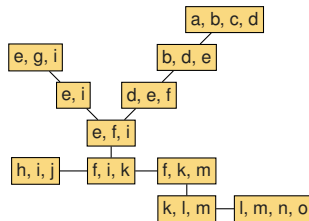
A 3-lean tree decomposition of  $G$

- Tree decomposition:
  1. All vertices and edges are covered by bags
  2. For each vertex  $v$ , the bags containing  $v$  form a connected subtree
- $k$ -lean:
  1. The **adhesions** (i.e. intersections of adjacent bags) have size  $< k$

## k-Lean Tree Decompositions



Graph G

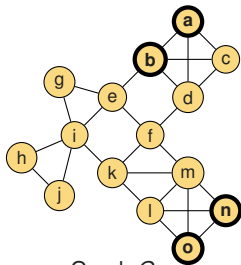


A 3-lean tree decomposition of G

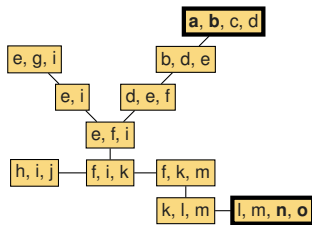
- Tree decomposition:
  1. All vertices and edges are covered by bags
  2. For each vertex  $v$ , the bags containing  $v$  form a connected subtree
- $k$ -lean:
  1. The **adhesions** (i.e. intersections of adjacent bags) have size  $< k$
  2. For each pair of bags  $B_1, B_2$  and subsets  $X_1 \subseteq B_1, X_2 \subseteq B_2$  with  $|X_1| = |X_2| \leq k$ , the sets  $X_1$  and  $X_2$  can be linked by vertex-disjoint paths iff there is no  $(B_1, B_2)$ -adhesion of size  $< |X_1| = |X_2|$



## k-Lean Tree Decompositions



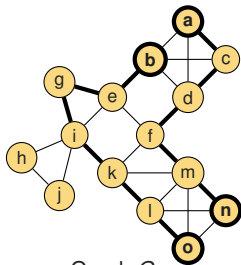
Graph G



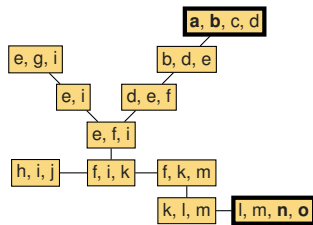
A 3-lean tree decomposition of G

- Tree decomposition:
  1. All vertices and edges are covered by bags
  2. For each vertex  $v$ , the bags containing  $v$  form a connected subtree
- $k$ -lean:
  1. The **adhesions** (i.e. intersections of adjacent bags) have size  $< k$
  2. For each pair of bags  $B_1, B_2$  and subsets  $X_1 \subseteq B_1, X_2 \subseteq B_2$  with  $|X_1| = |X_2| \leq k$ , the sets  $X_1$  and  $X_2$  can be linked by vertex-disjoint paths iff there is no  $(B_1, B_2)$ -adhesion of size  $< |X_1| = |X_2|$

## k-Lean Tree Decompositions



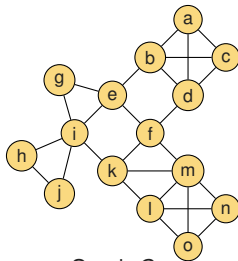
Graph G



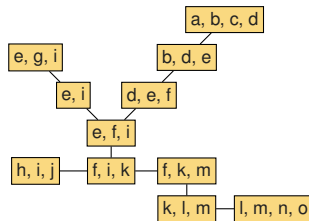
A 3-lean tree decomposition of G

- Tree decomposition:
  1. All vertices and edges are covered by bags
  2. For each vertex  $v$ , the bags containing  $v$  form a connected subtree
- $k$ -lean:
  1. The **adhesions** (i.e. intersections of adjacent bags) have size  $< k$
  2. For each pair of bags  $B_1, B_2$  and subsets  $X_1 \subseteq B_1, X_2 \subseteq B_2$  with  $|X_1| = |X_2| \leq k$ , the sets  $X_1$  and  $X_2$  can be linked by vertex-disjoint paths iff there is no  $(B_1, B_2)$ -adhesion of size  $< |X_1| = |X_2|$

## k-Lean Tree Decompositions



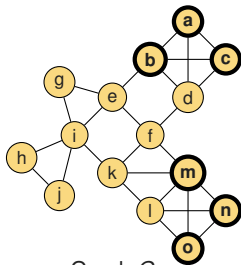
Graph G



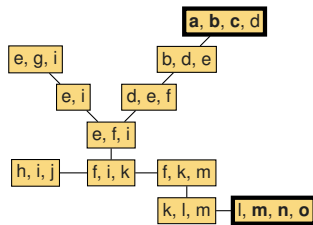
A 3-lean tree decomposition of G

- Tree decomposition:
  1. All vertices and edges are covered by bags
  2. For each vertex  $v$ , the bags containing  $v$  form a connected subtree
- $k$ -lean:
  1. The **adhesions** (i.e. intersections of adjacent bags) have size  $< k$
  2. For each pair of bags  $B_1, B_2$  and subsets  $X_1 \subseteq B_1, X_2 \subseteq B_2$  with  $|X_1| = |X_2| \leq k$ , the sets  $X_1$  and  $X_2$  can be linked by vertex-disjoint paths iff there is no  $(B_1, B_2)$ -adhesion of size  $< |X_1| = |X_2|$

## k-Lean Tree Decompositions



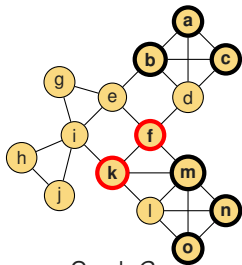
Graph G



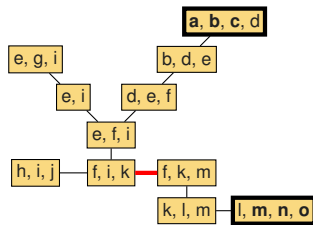
A 3-lean tree decomposition of G

- Tree decomposition:
  1. All vertices and edges are covered by bags
  2. For each vertex  $v$ , the bags containing  $v$  form a connected subtree
- $k$ -lean:
  1. The **adhesions** (i.e. intersections of adjacent bags) have size  $< k$
  2. For each pair of bags  $B_1, B_2$  and subsets  $X_1 \subseteq B_1, X_2 \subseteq B_2$  with  $|X_1| = |X_2| \leq k$ , the sets  $X_1$  and  $X_2$  can be linked by vertex-disjoint paths iff there is no  $(B_1, B_2)$ -adhesion of size  $< |X_1| = |X_2|$

## $k$ -Lean Tree Decompositions



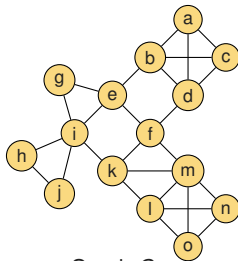
Graph  $G$



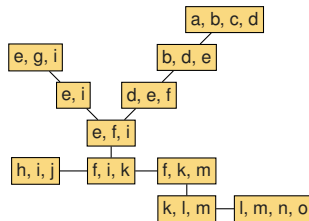
A 3-lean tree decomposition of  $G$

- Tree decomposition:
  1. All vertices and edges are covered by bags
  2. For each vertex  $v$ , the bags containing  $v$  form a connected subtree
- $k$ -lean:
  1. The **adhesions** (i.e. intersections of adjacent bags) have size  $< k$
  2. For each pair of bags  $B_1, B_2$  and subsets  $X_1 \subseteq B_1, X_2 \subseteq B_2$  with  $|X_1| = |X_2| \leq k$ , the sets  $X_1$  and  $X_2$  can be linked by vertex-disjoint paths iff there is no  $(B_1, B_2)$ -adhesion of size  $< |X_1| = |X_2|$

## k-Lean Tree Decompositions



Graph G



A 3-lean tree decomposition of G

- Tree decomposition:
  1. All vertices and edges are covered by bags
  2. For each vertex  $v$ , the bags containing  $v$  form a connected subtree
- $k$ -lean:
  1. The **adhesions** (i.e. intersections of adjacent bags) have size  $< k$
  2. For each pair of bags  $B_1, B_2$  and subsets  $X_1 \subseteq B_1, X_2 \subseteq B_2$  with  $|X_1| = |X_2| \leq k$ , the sets  $X_1$  and  $X_2$  can be linked by vertex-disjoint paths iff there is no  $(B_1, B_2)$ -adhesion of size  $< |X_1| = |X_2|$
- Defined by [Thomas '90] (for  $k = \infty$ ), and [Carmesin, Diestel, Hamann, and Hundertmark '14]

# The algorithm

# The algorithm

Part 1: Proof that “improver algorithm” implies the algorithm (Inspired by [\[Bodlaender '96\]](#))

Part 2: The improver algorithm (Inspired by [\[Graph Minors X., Robertson & Seymour '91\]](#))



## Part 1: Improver algorithm implies the algorithm

### Improver algorithm:

Input: A “weakly- $k$ -lean” tree decomposition:

- Adhesion size  $< 2k$
- Any two subsets  $X_1, X_2 \subseteq B$  of a bag  $B$  of size  $|X_1|, |X_2| \geq 2k$  can be linked by  $k$  vertex-disjoint paths

Output:  $k$ -lean tree decomposition

## Part 1: Improver algorithm implies the algorithm

### Improver algorithm:

Input: A “weakly- $k$ -lean” tree decomposition:

- Adhesion size  $< 2k$
- Any two subsets  $X_1, X_2 \subseteq B$  of a bag  $B$  of size  $|X_1|, |X_2| \geq 2k$  can be linked by  $k$  vertex-disjoint paths

Output:  $k$ -lean tree decomposition

### Lemma

If there is improver algorithm with running time  $f(k) \cdot m$ , then there is an algorithm that in time  $\text{poly}(k) \cdot f(k) \cdot m$  computes a  $k$ -lean tree decomposition.

## Part 1: Improver algorithm implies the algorithm

### Improver algorithm:

Input: A “weakly- $k$ -lean” tree decomposition:

- Adhesion size  $< 2k$
- Any two subsets  $X_1, X_2 \subseteq B$  of a bag  $B$  of size  $|X_1|, |X_2| \geq 2k$  can be linked by  $k$  vertex-disjoint paths

Output:  $k$ -lean tree decomposition

### Lemma

If there is improver algorithm with running time  $f(k) \cdot m$ , then there is an algorithm that in time  $\text{poly}(k) \cdot f(k) \cdot m$  computes a  $k$ -lean tree decomposition.

Proof idea:

- Self-reduction by recursion contracting a linear-size matching à la [Bodlaender '96]
- Sparsification by [Nagamochi-Ibaraki '92]

## Part 2: The improver algorithm

### Improver algorithm:

Input: A “weakly- $k$ -lean” tree decomposition:

- Adhesion size  $< 2k$
- Any two subsets  $X_1, X_2 \subseteq B$  of a bag  $B$  of size  $|X_1|, |X_2| \geq 2k$  can be linked by  $k$  vertex-disjoint paths

Output:  $k$ -lean tree decomposition

### Lemma

There is an improver algorithm with running time  $k^{O(k^2)}m$ .

## Part 2: The improver algorithm

### Improver algorithm:

Input: A “weakly- $k$ -lean” tree decomposition:

- Adhesion size  $< 2k$
- Any two subsets  $X_1, X_2 \subseteq B$  of a bag  $B$  of size  $|X_1|, |X_2| \geq 2k$  can be linked by  $k$  vertex-disjoint paths

Output:  $k$ -lean tree decomposition

### Lemma

There is an improver algorithm with running time  $k^{O(k^2)}m$ .

Proof idea:

- Slowly improve the properties of the input tree decomposition (in 6 consecutive steps)
- Key tool: Decomposition by **doubly well-linked separations**

## Part 2: The improver algorithm

### Improver algorithm:

Input: A “weakly- $k$ -lean” tree decomposition:

- Adhesion size  $< 2k$
- Any two subsets  $X_1, X_2 \subseteq B$  of a bag  $B$  of size  $|X_1|, |X_2| \geq 2k$  can be linked by  $k$  vertex-disjoint paths

Output:  $k$ -lean tree decomposition

### Lemma

There is an improver algorithm with running time  $k^{O(k^2)}m$ .

Proof idea:

- Slowly improve the properties of the input tree decomposition (in 6 consecutive steps)
- Key tool: Decomposition by **doubly well-linked separations**
  - ▶ Separation  $(L, S, R)$ , so that  $S$  is well-linked in both  $G[L \cup S]$  and  $G[S \cup R]$
  - ▶ Allows greedy decomposition

## Conclusion

- $k^{\mathcal{O}(k^2)}m$  time algorithm for  $k$ -lean tree decomposition, implying algorithms for:
  - ▶  $k$ -edge-connected components (long-standing open problem)
  - ▶  $k$ -vertex connectivity
  - ▶  $k$ -unbreakable tree decomposition
  - ▶  $k$ -Gomory-Hu tree (for both edge- and element-connectivity)

## Conclusion

- $k^{O(k^2)}m$  time algorithm for  $k$ -lean tree decomposition, implying algorithms for:
  - ▶  $k$ -edge-connected components (long-standing open problem)
  - ▶  $k$ -vertex connectivity
  - ▶  $k$ -unbreakable tree decomposition
  - ▶  $k$ -Gomory-Hu tree (for both edge- and element-connectivity)

### Main techniques:

- Recursive matching contraction compression (inspired by [Bodlaender '96])
- Decomposition by doubly well-linked separations (inspired by [Graph Minors X., Robertson & Seymour '91])



## Conclusion

- $k^{O(k^2)}m$  time algorithm for  $k$ -lean tree decomposition, implying algorithms for:
  - ▶  $k$ -edge-connected components (long-standing open problem)
  - ▶  $k$ -vertex connectivity
  - ▶  $k$ -unbreakable tree decomposition
  - ▶  $k$ -Gomory-Hu tree (for both edge- and element-connectivity)

### Main techniques:

- Recursive matching contraction compression (inspired by [Bodlaender '96])
- Decomposition by doubly well-linked separations (inspired by [Graph Minors X., Robertson & Seymour '91])

### Open problems/future work:

- Improve running time to  $2^{o(k^2)}m$  (even e.g. just for  $k$ -edge-connected components)
- Simplify

## Conclusion

- $k^{O(k^2)}m$  time algorithm for  $k$ -lean tree decomposition, implying algorithms for:
  - ▶  $k$ -edge-connected components (long-standing open problem)
  - ▶  $k$ -vertex connectivity
  - ▶  $k$ -unbreakable tree decomposition
  - ▶  $k$ -Gomory-Hu tree (for both edge- and element-connectivity)

### Main techniques:

- Recursive matching contraction compression (inspired by [Bodlaender '96])
- Decomposition by doubly well-linked separations (inspired by [Graph Minors X., Robertson & Seymour '91])

### Open problems/future work:

- Improve running time to  $2^{o(k^2)}m$  (even e.g. just for  $k$ -edge-connected components)
- Simplify

Thank you!