

# Dynamic Treewidth

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based on joint work with Konrad Majewski, Wojciech Nadara,  
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- [Goranci,Räcke,Saranurak,Tan’21]:  $n^{o(1)}$  amortized time  $n^{o(1)}$ -approximate tree decomposition. Not suitable for dynamic programming.

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### Theorem (This work)

There is a data structure that is initialized with an integer  $k$  and an empty  $n$ -vertex graph  $G$ , and maintains a tree decomposition of  $G$  of width at most  $6k + 5$  under edge additions and deletions in amortized update time  $\mathcal{O}_k(2^{\sqrt{\log n \log \log n}})$ , under the promise that the treewidth of  $G$  never exceeds  $k$ .

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Moreover

- the data structure can maintain the run of any tree automaton with evaluation time  $\mathcal{O}_k(1)$  within the same running time
- the data structure persists even when the treewidth of  $G$  exceeds  $k$ , in that case returning a marker “Treewidth too large” instead of maintaining the automaton

## Example application

### Corollary

Let  $H$  be fixed planar graph. There is a dynamic algorithm with  $\mathcal{O}_H(2^{\sqrt{\log n} \log \log n})$  amortized update time for maintaining whether  $G$  contains  $H$  as a minor.

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### Proof:

- By the Grid Minor Theorem [Robertson&Seymour'85], there exists  $k$  so that every graph of treewidth  $> k$  contains  $H$  as a minor
- Use dynamic treewidth data structure with this  $k$  and a tree automaton that tests for  $H$  as a minor by dynamic programming □

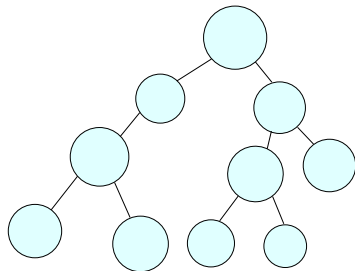


# The algorithm

# General plan

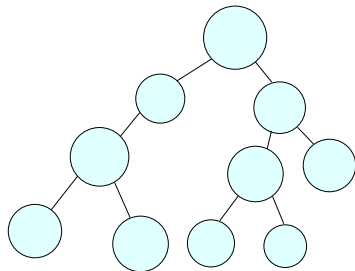
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- Goal: Maintain a rooted binary tree decomposition of width  $6k + 5$  and depth  $d = 2^{\mathcal{O}_k(\sqrt{\log n \log \log n})}$



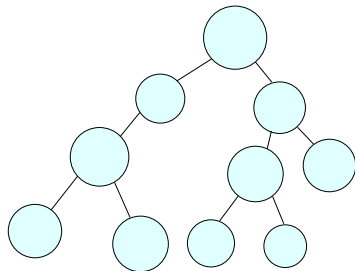
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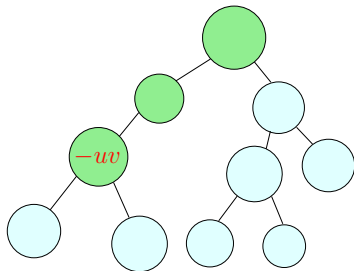
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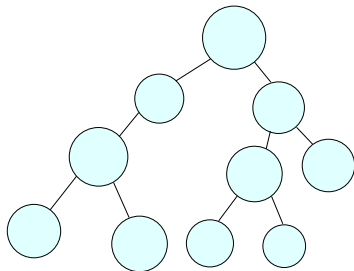
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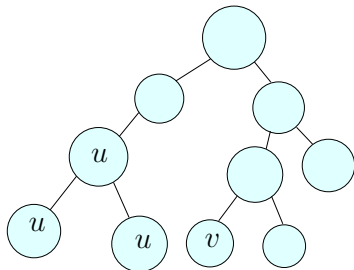
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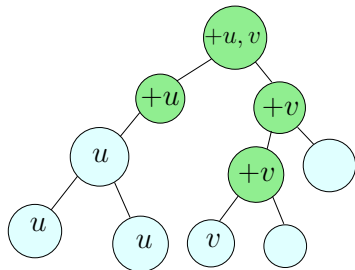
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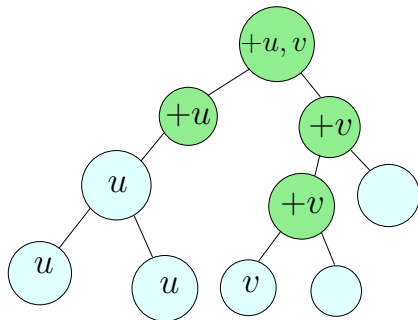


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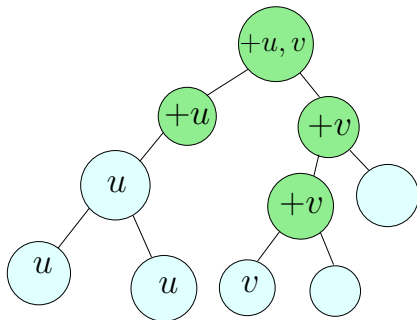


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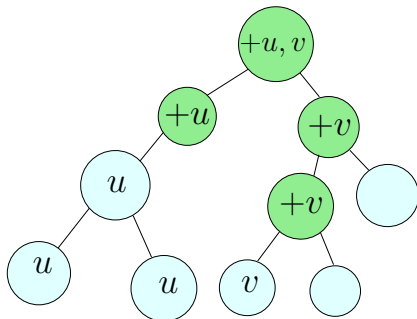
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- Solution: a *Refinement operation* to re-compute the tree decomposition on these bags

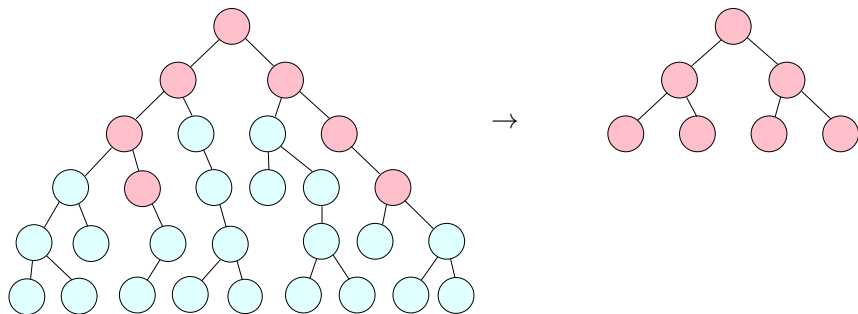


# Refinement operation



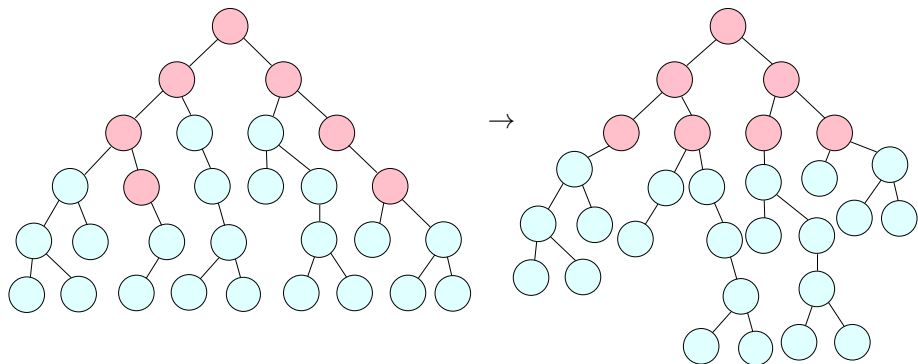
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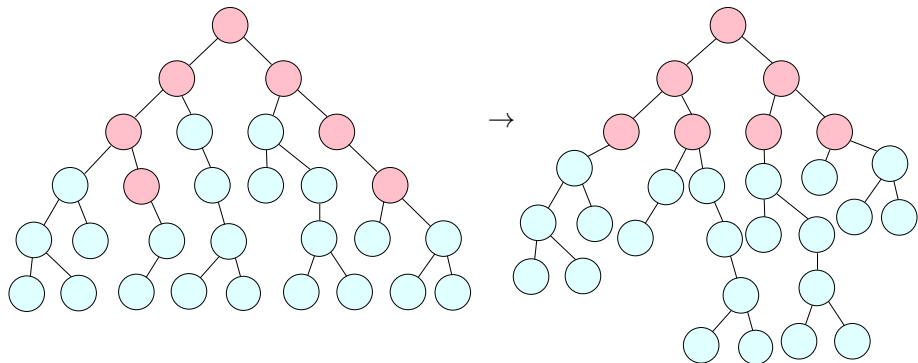
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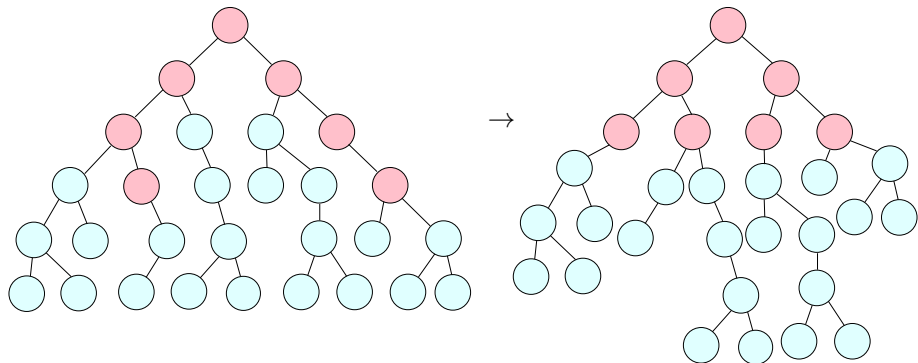
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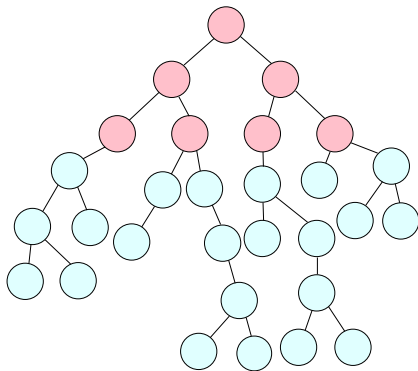


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- Builds on the improvement operation of [K & Lokshantov'23], also uses the dealternation lemma of [Bojańczyk&Pilipczuk'22] and Bodlaender-Hagerup-lemma



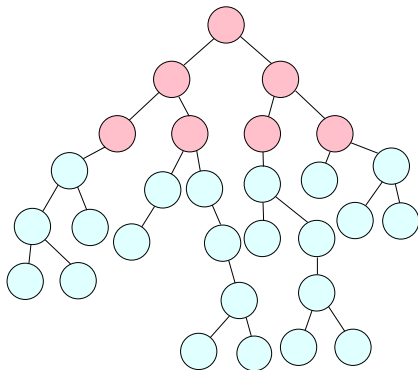
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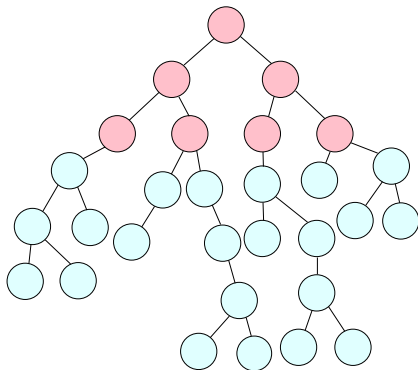
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- Solution: A depth-reduction scheme by using the refinement operation and a potential function



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⇒ We can decrease potential in time proportional to the decrease

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### Lemma

If depth  $> 2^{\mathcal{O}_k(\sqrt{\log n \log \log n})}$ , then exists prefix  $T_{\text{pref}}$  so that  $\phi(T') < \phi(T) - \Omega(\phi(T_{\text{pref}}))$ .

⇒ We can decrease potential in time proportional to the decrease

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## Depth-reduction scheme

- Potential function of form  $\phi(T) = \sum_{t \in V(T)} k^{10 \cdot |B_t|} \cdot \text{height}(t)$
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⇒ Can keep depth at most  $2^{\mathcal{O}_k(\sqrt{\log n \log \log n})}$  with amortized time complexity  $2^{\mathcal{O}_k(\sqrt{\log n \log \log n})}$

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  - ▶ Dynamic  $k$ -DISJOINT PATHS on planar graphs?

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