

Dynamic Treewidth in Logarithmic Time

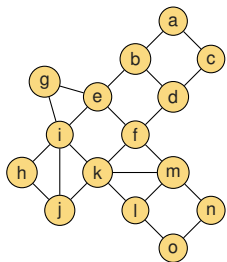
Tuukka Korhonen



FOCS 2025

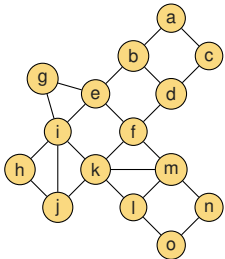
16 December 2025

Treewidth

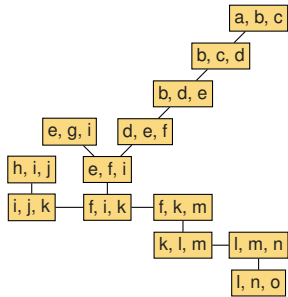


Graph G

Treewidth

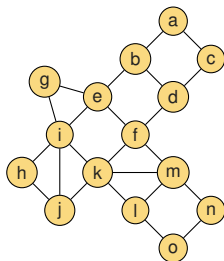


Graph G

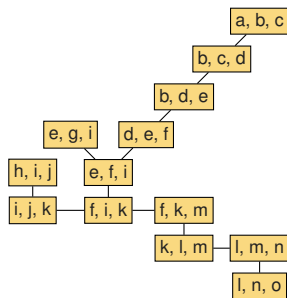


A tree decomposition of G

Treewidth



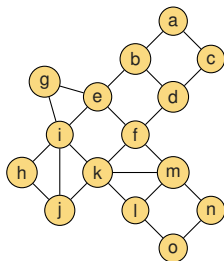
Graph G



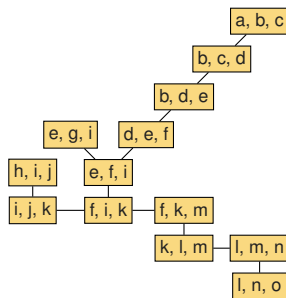
A tree decomposition of G

1. Every vertex should be in a bag

Treewidth



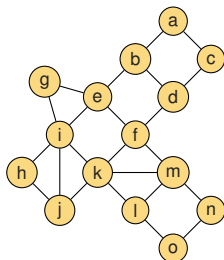
Graph G



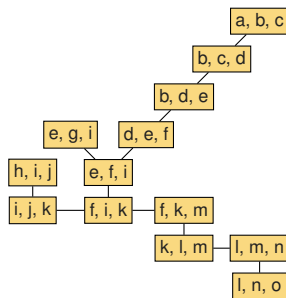
A tree decomposition of G

1. Every vertex should be in a bag
2. Every edge should be in a bag

Treewidth



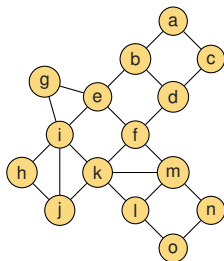
Graph G



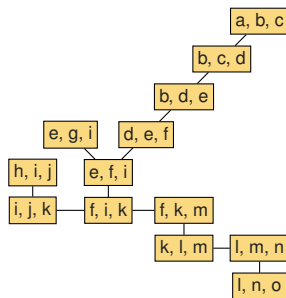
A tree decomposition of G

1. Every vertex should be in a bag
2. Every edge should be in a bag
3. For every vertex v , the bags containing v should form a connected subtree

Treewidth



Graph G

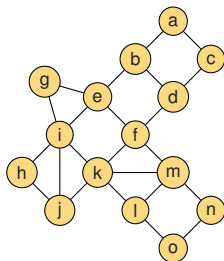


A tree decomposition of G

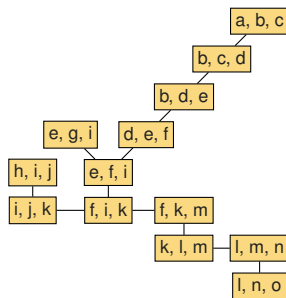
Width = 2

1. Every vertex should be in a bag
2. Every edge should be in a bag
3. For every vertex v , the bags containing v should form a connected subtree
4. Width = maximum bag size $- 1$

Treewidth



Graph G
Treewidth 2



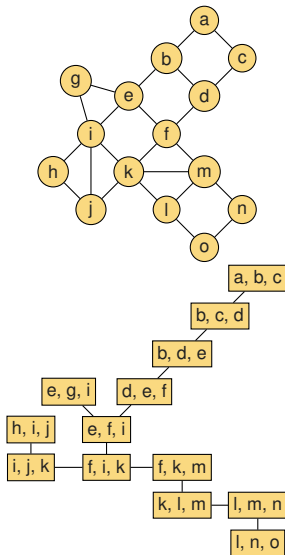
A tree decomposition of G
Width = 2

1. Every vertex should be in a bag
2. Every edge should be in a bag
3. For every vertex v , the bags containing v should form a connected subtree
4. Width = maximum bag size $- 1$
5. Treewidth of G = minimum width of tree decomposition of G

[Robertson & Seymour'84, Arnborg & Proskurowski'89, Bertele & Brioschi'72, Halin'76]

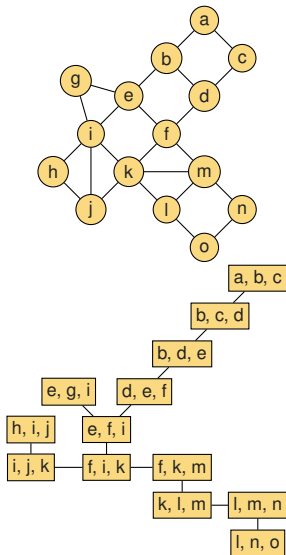
Why treewidth?

- Algorithms for **trees** often generalize to algorithms for graphs of **small treewidth**



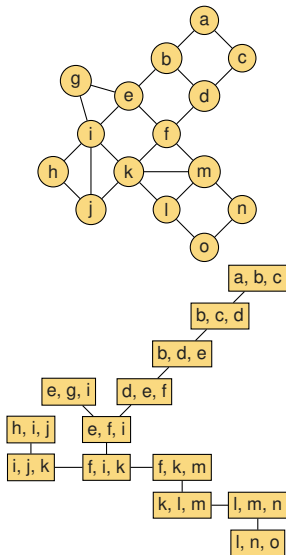
Why treewidth?

- Algorithms for **trees** often generalize to algorithms for graphs of **small treewidth**
- Example: Maximum independent set in $\mathcal{O}(2^k \cdot n)$ time on treewidth- k graphs



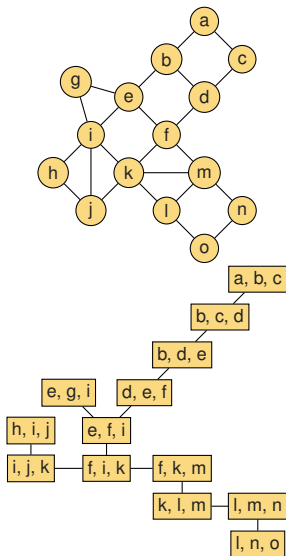
Why treewidth?

- Algorithms for **trees** often generalize to algorithms for graphs of **small treewidth**
- Example: Maximum independent set in $\mathcal{O}(2^k \cdot n)$ time on treewidth- k graphs
- Courcelle's theorem** gives $f(k) \cdot n$ time algorithms for all problems definable in **MSO**-logic



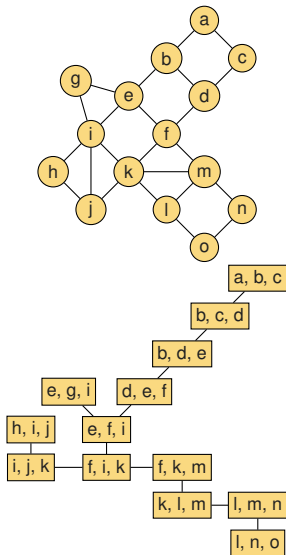
Why treewidth?

- Algorithms for **trees** often generalize to algorithms for graphs of **small treewidth**
- Example: Maximum independent set in $\mathcal{O}(2^k \cdot n)$ time on treewidth- k graphs
- Courcelle's theorem** gives $f(k) \cdot n$ time algorithms for all problems definable in **MSO**-logic
- Need the tree decomposition!



Why treewidth?

- Algorithms for **trees** often generalize to algorithms for graphs of **small treewidth**
- Example: Maximum independent set in $\mathcal{O}(2^k \cdot n)$ time on treewidth- k graphs
- Courcelle's theorem** gives $f(k) \cdot n$ time algorithms for all problems definable in **MSO**-logic
- Need the tree decomposition!
- $2^{\mathcal{O}(k^3)} n$ time algorithm to compute an optimum-width tree decomposition [Bodlaender '96]
- $2^{\mathcal{O}(k)} n$ time for 2-approximation [K. '21]
- $n^{\mathcal{O}(1)}$ time for $\mathcal{O}(\sqrt{\log k})$ -approximation [Feige, Hajiaghayi, Lee'08]



Dynamic treewidth

Question [Bodlaender '93, Dvořák, Kupec & Tůma '14, Alman, Mnich & Vassilevska Williams '20]

Can we efficiently maintain a tree decomposition of a dynamic graph with bounded treewidth?

Dynamic treewidth

Question [Bodlaender '93, Dvořák, Kupec & Tůma '14, Alman, Mnich & Vassilevska Williams '20]

Can we efficiently maintain a tree decomposition of a dynamic graph with bounded treewidth?

- Would also like to maintain dynamic programming on the decomposition (dynamic Courcelle's theorem)

Dynamic treewidth

Question [Bodlaender '93, Dvořák, Kupec & Tůma '14, Alman, Mnich & Vassilevska Williams '20]

Can we efficiently maintain a tree decomposition of a dynamic graph with bounded treewidth?

- Would also like to maintain dynamic programming on the decomposition (dynamic Courcelle's theorem)

Previous work:

Dynamic treewidth

Question [Bodlaender '93, Dvořák, Kupec & Tůma '14, Alman, Mnich & Vassilevska Williams '20]

Can we efficiently maintain a tree decomposition of a dynamic graph with bounded treewidth?

- Would also like to maintain dynamic programming on the decomposition (**dynamic Courcelle's theorem**)

Previous work:

- **Treewidth-1** (dynamic forests): $\mathcal{O}(\log n)$ update time [Sleator & Tarjan'83, Frederickson'85,97, Alstrup, Holm, de Lichtenberg, Thorup'05...]

Dynamic treewidth

Question [Bodlaender '93, Dvořák, Kupec & Tůma '14, Alman, Mnich & Vassilevska Williams '20]

Can we efficiently maintain a tree decomposition of a dynamic graph with bounded treewidth?

- Would also like to maintain dynamic programming on the decomposition (**dynamic Courcelle's theorem**)

Previous work:

- **Treewidth-1** (dynamic forests): $\mathcal{O}(\log n)$ update time [Sleator & Tarjan'83, Frederickson'85,97, Alstrup, Holm, de Lichtenberg, Thorup'05...]
- **Treewidth-2**: $\mathcal{O}(\log n)$ update time [Bodlaender'93]

Dynamic treewidth

Question [Bodlaender '93, Dvořák, Kupec & Tůma '14, Alman, Mnich & Vassilevska Williams '20]

Can we efficiently maintain a tree decomposition of a dynamic graph with bounded treewidth?

- Would also like to maintain dynamic programming on the decomposition (dynamic Courcelle's theorem)

Previous work:

- **Treewidth-1** (dynamic forests): $\mathcal{O}(\log n)$ update time [Sleator & Tarjan'83, Frederickson'85,97, Alstrup, Holm, de Lichtenberg, Thorup'05...]
- **Treewidth-2**: $\mathcal{O}(\log n)$ update time [Bodlaender'93]
- **Treewidth- k** : $n^{o(1)}$ amortized update time $n^{o(1)}$ -approximate tree decomposition on bounded-degree graphs. [Goranci, Räcke, Saranurak, Tan '21]

Dynamic treewidth

Question [Bodlaender '93, Dvořák, Kupec & Tůma '14, Alman, Mnich & Vassilevska Williams '20]

Can we efficiently maintain a tree decomposition of a dynamic graph with bounded treewidth?

- Would also like to maintain dynamic programming on the decomposition (**dynamic Courcelle's theorem**)

Previous work:

- **Treewidth-1** (dynamic forests): $\mathcal{O}(\log n)$ update time [Sleator & Tarjan'83, Frederickson'85,97, Alstrup, Holm, de Lichtenberg, Thorup'05...]
- **Treewidth-2**: $\mathcal{O}(\log n)$ update time [Bodlaender'93]
- **Treewidth- k** : $n^{o(1)}$ amortized update time $n^{o(1)}$ -approximate tree decomposition on bounded-degree graphs. [Goranci, Räcke, Saranurak, Tan '21] (not suitable for dynamic Courcelle's theorem)

Dynamic treewidth

Question [Bodlaender '93, Dvořák, Kupec & Tůma '14, Alman, Mnich & Vassilevska Williams '20]

Can we efficiently maintain a tree decomposition of a dynamic graph with bounded treewidth?

- Would also like to maintain dynamic programming on the decomposition (dynamic Courcelle's theorem)

Previous work:

- Treewidth-1 (dynamic forests): $\mathcal{O}(\log n)$ update time [Sleator & Tarjan'83, Frederickson'85,97, Alstrup, Holm, de Lichtenberg, Thorup'05...]
- Treewidth-2: $\mathcal{O}(\log n)$ update time [Bodlaender'93]
- Treewidth- k : $n^{o(1)}$ amortized update time $n^{o(1)}$ -approximate tree decomposition on bounded-degree graphs. [Goranci, Räcke, Saranurak, Tan '21] (not suitable for dynamic Courcelle's theorem)
- Treewidth- k : $2^{k^{o(1)}} n^{o(1)}$ amortized update time 6-approximate tree decomposition. [K., Majewski, Nadara, Pilipczuk, Sokołowski '23]

Dynamic treewidth

Question [Bodlaender '93, Dvořák, Kupec & Tůma '14, Alman, Mnich & Vassilevska Williams '20]

Can we efficiently maintain a tree decomposition of a dynamic graph with bounded treewidth?

- Would also like to maintain dynamic programming on the decomposition (**dynamic Courcelle's theorem**)

Previous work:

- **Treewidth-1** (dynamic forests): $\mathcal{O}(\log n)$ update time [Sleator & Tarjan'83, Frederickson'85,97, Alstrup, Holm, de Lichtenberg, Thorup'05...]
- **Treewidth-2**: $\mathcal{O}(\log n)$ update time [Bodlaender'93]
- **Treewidth- k** : $n^{o(1)}$ amortized update time $n^{o(1)}$ -approximate tree decomposition on bounded-degree graphs. [Goranci, Räcke, Saranurak, Tan '21] (not suitable for dynamic Courcelle's theorem)
- **Treewidth- k** : $2^{k^{o(1)}} n^{o(1)}$ amortized update time **6**-approximate tree decomposition. [K., Majewski, Nadara, Pilipczuk, Sokołowski '23]

Theorem (This work)

$2^{O(k)} \log n$ amortized update time **9**-approximate tree decomposition.

Dynamic treewidth

Question [Bodlaender '93, Dvořák, Kupec & Tůma '14, Alman, Mnich & Vassilevska Williams '20]

Can we efficiently maintain a tree decomposition of a dynamic graph with bounded treewidth?

- Would also like to maintain dynamic programming on the decomposition (**dynamic Courcelle's theorem**)

Previous work:

- **Treewidth-1** (dynamic forests): $\mathcal{O}(\log n)$ update time [Sleator & Tarjan'83, Frederickson'85,97, Alstrup, Holm, de Lichtenberg, Thorup'05...]
- **Treewidth-2**: $\mathcal{O}(\log n)$ update time [Bodlaender'93]
- **Treewidth- k** : $n^{o(1)}$ amortized update time $n^{o(1)}$ -approximate tree decomposition on bounded-degree graphs. [Goranci, Räcke, Saranurak, Tan '21] (not suitable for dynamic Courcelle's theorem)
- **Treewidth- k** : $2^{k^{o(1)}} n^{o(1)}$ amortized update time **6**-approximate tree decomposition. [K., Majewski, Nadara, Pilipczuk, Sokołowski '23]

Theorem (This work)

$2^{\mathcal{O}(k)} \log n$ amortized update time **9**-approximate tree decomposition.

- Arguably optimal update time: $\Omega(\log n)$ needed for dynamic forests [Patrascu&Demaine'04]

Detailed Theorem Statement

Theorem (This work)

$2^{\mathcal{O}(k)} \log n$ amortized update time 9 -approximate tree decomposition.

Detailed Theorem Statement

Theorem (This work)

$2^{\mathcal{O}(k)} \log n$ amortized update time 9 -approximate tree decomposition.

There is data structure that:

- is initialized with an integer k and an edgeless n -vertex graph G
- supports edge insertions/deletions in amortized time $2^{\mathcal{O}(k)} \log n$ under the promise that $\text{tw}(G) \leq k$
- maintains a tree decomposition of G of width at most $9 \cdot \text{tw}(G) + 8$

Detailed Theorem Statement

Theorem (This work)

$2^{\mathcal{O}(k)} \log n$ amortized update time 9-approximate tree decomposition.

There is data structure that:

- is initialized with an integer k and an edgeless n -vertex graph G
- supports edge insertions/deletions in amortized time $2^{\mathcal{O}(k)} \log n$ under the promise that $\text{tw}(G) \leq k$
- maintains a tree decomposition of G of width at most $9 \cdot \text{tw}(G) + 8$
- can also maintain any **dynamic programming scheme** on the decomposition within similar running time (formalized by tree decomposition automata)

Detailed Theorem Statement

Theorem (This work)

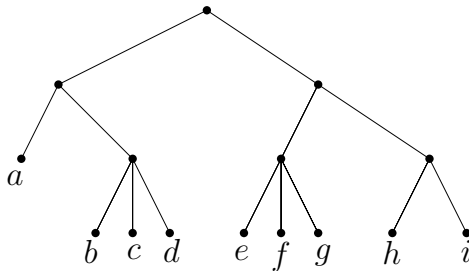
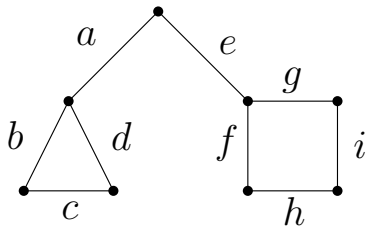
$2^{\mathcal{O}(k)} \log n$ amortized update time 9-approximate tree decomposition.

There is data structure that:

- is initialized with an integer k and an edgeless n -vertex graph G
 - supports edge insertions/deletions in amortized time $2^{\mathcal{O}(k)} \log n$ under the promise that $\text{tw}(G) \leq k$
 - maintains a tree decomposition of G of width at most $9 \cdot \text{tw}(G) + 8$
 - can also maintain any **dynamic programming scheme** on the decomposition within similar running time (formalized by tree decomposition automata)
- ⇒ Dynamic Courcelle's theorem in $f(k) \cdot \log n$ amortized update time

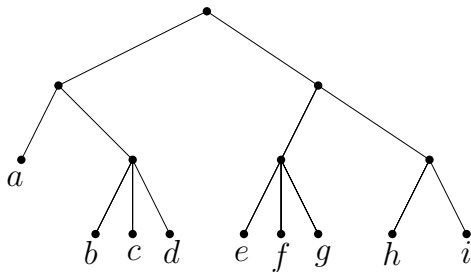
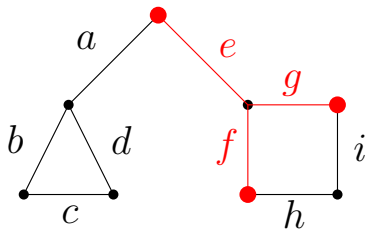
The algorithm

Maintained decomposition



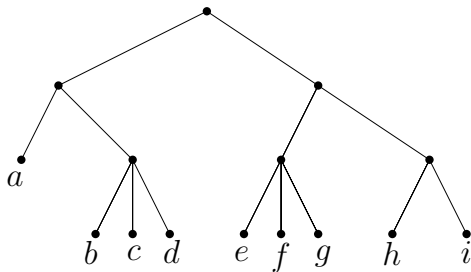
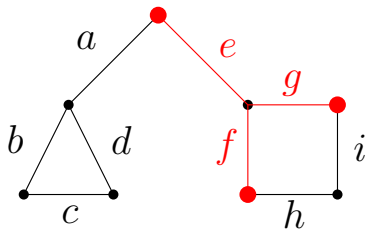
- **Branch decomposition:** Rooted tree whose leaves correspond to the edges of the graph

Maintained decomposition



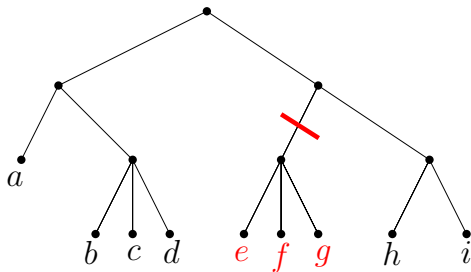
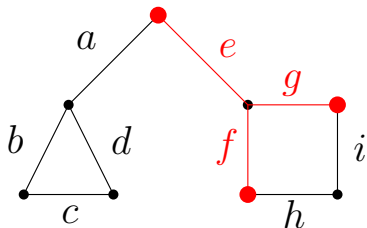
- **Branch decomposition:** Rooted tree whose leaves correspond to the edges of the graph
- **Boundary** $\partial(F)$ of a set of edges $F \subseteq E$: The vertices incident to edges from both F and $E \setminus F$.

Maintained decomposition



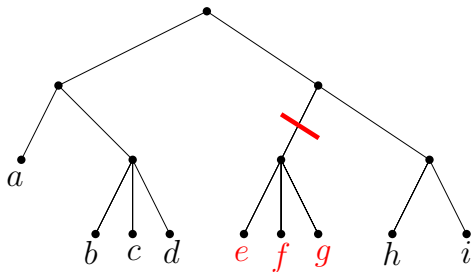
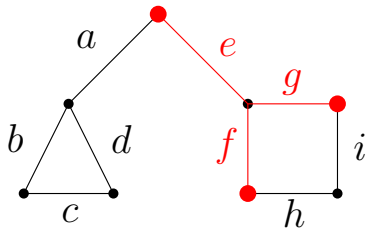
- **Branch decomposition:** Rooted tree whose leaves correspond to the edges of the graph
- **Boundary** $\partial(F)$ of a set of edges $F \subseteq E$: The vertices incident to edges from both F and $E \setminus F$.
- A set of edges $F \subseteq E$ is **well-linked** if it cannot be partitioned to (C_1, C_2) so that $|\partial(C_1)| < |\partial(F)|$ and $|\partial(C_2)| < |\partial(F)|$

Maintained decomposition



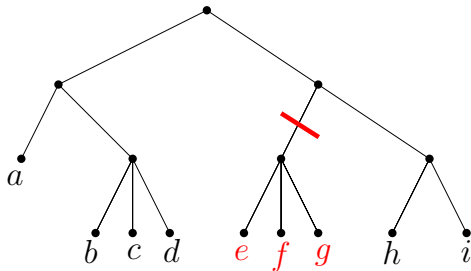
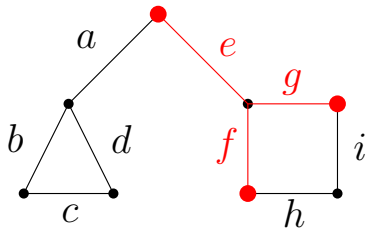
- **Branch decomposition:** Rooted tree whose leaves correspond to the edges of the graph
- **Boundary** $\partial(F)$ of a set of edges $F \subseteq E$: The vertices incident to edges from both F and $E \setminus F$.
- A set of edges $F \subseteq E$ is **well-linked** if it cannot be partitioned to (C_1, C_2) so that $|\partial(C_1)| < |\partial(F)|$ and $|\partial(C_2)| < |\partial(F)|$
- Want to maintain: Every edge set corresponding to a subtree is well-linked “downwards well-linkedness”

Maintained decomposition



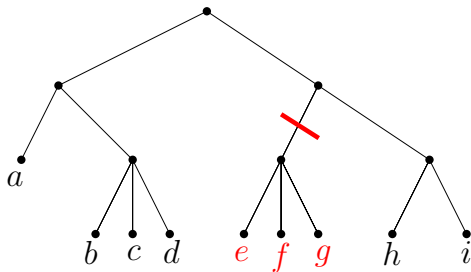
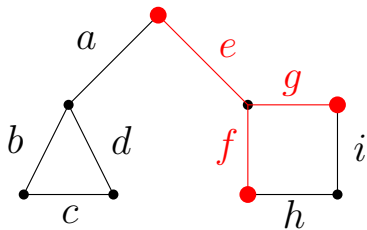
- **Branch decomposition:** Rooted tree whose leaves correspond to the edges of the graph
- **Boundary** $\partial(F)$ of a set of edges $F \subseteq E$: The vertices incident to edges from both F and $E \setminus F$.
- A set of edges $F \subseteq E$ is **well-linked** if it cannot be partitioned to (C_1, C_2) so that $|\partial(C_1)| < |\partial(F)|$ and $|\partial(C_2)| < |\partial(F)|$
- Want to maintain: Every edge set corresponding to a subtree is well-linked “downwards well-linkedness”
⇒ Boundaries have size $\mathcal{O}(k)$

Maintained decomposition



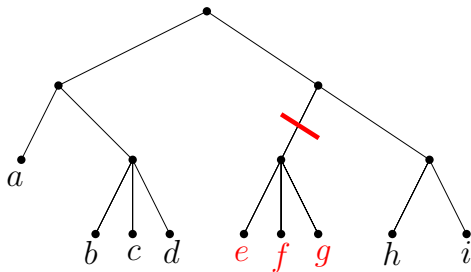
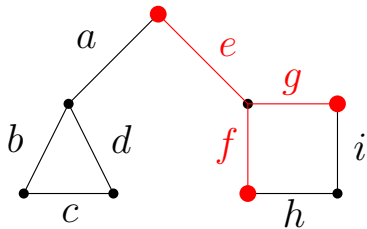
- **Branch decomposition:** Rooted tree whose leaves correspond to the edges of the graph
- **Boundary** $\partial(F)$ of a set of edges $F \subseteq E$: The vertices incident to edges from both F and $E \setminus F$.
- A set of edges $F \subseteq E$ is **well-linked** if it cannot be partitioned to (C_1, C_2) so that $|\partial(C_1)| < |\partial(F)|$ and $|\partial(C_2)| < |\partial(F)|$
- Want to maintain: Every edge set corresponding to a subtree is well-linked “downwards well-linkedness”
⇒ Boundaries have size $\mathcal{O}(k)$
- Also: Degree at most $2^{\mathcal{O}(k)}$

Maintained decomposition



- **Branch decomposition:** Rooted tree whose leaves correspond to the edges of the graph
- **Boundary** $\partial(F)$ of a set of edges $F \subseteq E$: The vertices incident to edges from both F and $E \setminus F$.
- A set of edges $F \subseteq E$ is **well-linked** if it cannot be partitioned to (C_1, C_2) so that $|\partial(C_1)| < |\partial(F)|$ and $|\partial(C_2)| < |\partial(F)|$
- Want to maintain: Every edge set corresponding to a subtree is well-linked “downwards well-linkedness”
⇒ Boundaries have size $\mathcal{O}(k)$
- Also: Degree at most $2^{\mathcal{O}(k)}$
⇒ Tree decomposition of width $2^{\mathcal{O}(k)}$ (later optimize to $\mathcal{O}(k)$)

Maintained decomposition

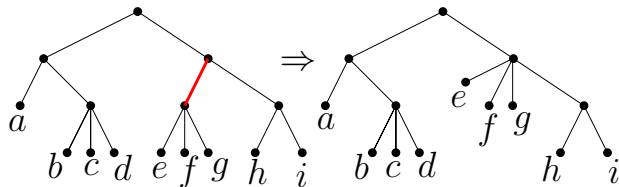


- **Branch decomposition**: Rooted tree whose leaves correspond to the edges of the graph
- **Boundary** $\partial(F)$ of a set of edges $F \subseteq E$: The vertices incident to edges from both F and $E \setminus F$.
- A set of edges $F \subseteq E$ is **well-linked** if it cannot be partitioned to (C_1, C_2) so that $|\partial(C_1)| < |\partial(F)|$ and $|\partial(C_2)| < |\partial(F)|$
- Want to maintain: Every edge set corresponding to a subtree is well-linked “downwards well-linkedness”
⇒ Boundaries have size $\mathcal{O}(k)$
- Also: Degree at most $2^{\mathcal{O}(k)}$
⇒ Tree decomposition of width $2^{\mathcal{O}(k)}$ (later optimize to $\mathcal{O}(k)$)
- Depth at most $2^{\mathcal{O}(k)} \log n$

Local rotations

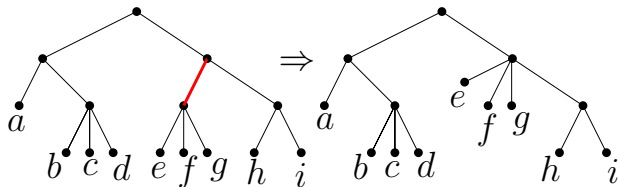
Local rotations

1. **Contraction:** Given an edge uv of the decomposition, contract it.



Local rotations

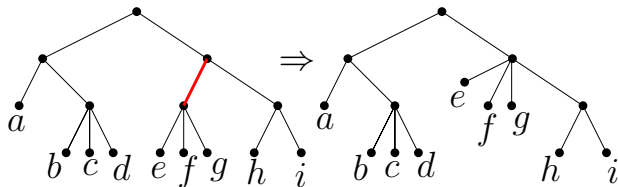
1. **Contraction:** Given an edge uv of the decomposition, contract it.
 - Maintains downwards well-linkedness



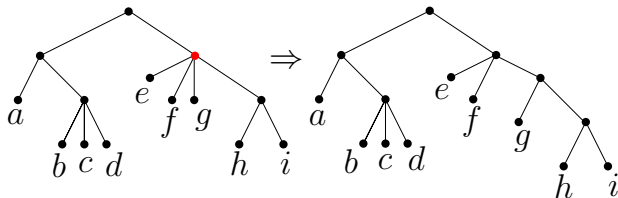
Local rotations

1. **Contraction:** Given an edge uv of the decomposition, contract it.

► Maintains downwards well-linkedness



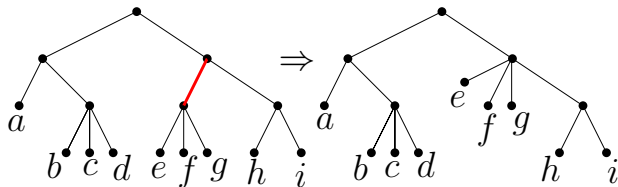
2. **Splitting:** Given a node of degree $> f(k) = 2^{O(k)}$, locally split it to multiple nodes



Local rotations

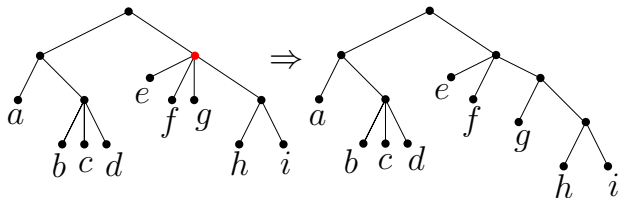
1. **Contraction:** Given an edge uv of the decomposition, contract it.

► Maintains downwards well-linkedness



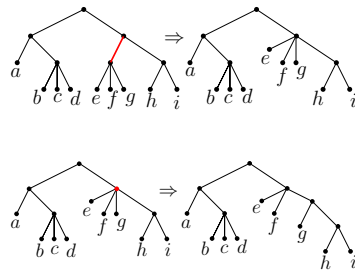
2. **Splitting:** Given a node of degree $> f(k) = 2^{O(k)}$, locally split it to multiple nodes

► **Lemma:** Can be done so that downwards well-linkedness is maintained



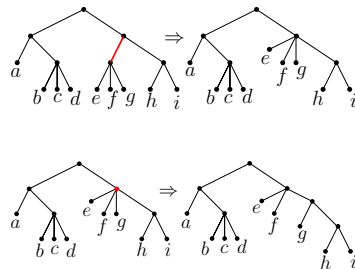
Approach

- **Idea:** Implement splay-tree-like rotations with the local rotations



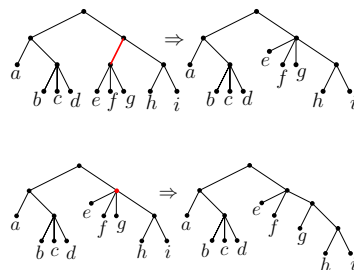
Approach

- **Idea:** Implement splay-tree-like rotations with the local rotations
- Potential-function: $\Phi(t) = (\#children(t) - 1) \cdot \log(size(t))$



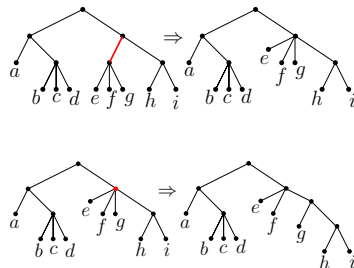
Approach

- **Idea:** Implement splay-tree-like rotations with the local rotations
- Potential-function: $\Phi(t) = (\#children(t) - 1) \cdot \log(size(t))$
- To facilitate edge insertions/deletions, additional self-loops on vertices



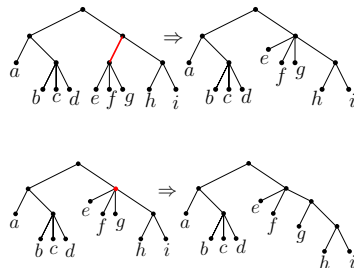
Approach

- **Idea:** Implement splay-tree-like rotations with the local rotations
- Potential-function: $\Phi(t) = (\#children(t) - 1) \cdot \log(size(t))$
- To facilitate edge insertions/deletions, additional self-loops on vertices
- To insert an edge uv :
 1. rotate the self-loops u and v to be children of the root
 2. insert uv as another child of the root
 3. re-balance



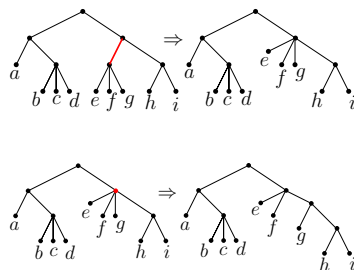
Approach

- **Idea:** Implement splay-tree-like rotations with the local rotations
- Potential-function: $\Phi(t) = (\#children(t) - 1) \cdot \log(size(t))$
- To facilitate edge insertions/deletions, additional self-loops on vertices
- To insert an edge uv :
 1. rotate the self-loops u and v to be children of the root
 2. insert uv as another child of the root
 3. re-balance
- Deletion of uv is similar



Approach

- **Idea:** Implement splay-tree-like rotations with the local rotations
- Potential-function: $\Phi(t) = (\#children(t) - 1) \cdot \log(size(t))$
- To facilitate edge insertions/deletions, additional self-loops on vertices
- To insert an edge uv :
 1. rotate the self-loops u and v to be children of the root
 2. insert uv as another child of the root
 3. re-balance
- Deletion of uv is similar
- **Post-processing:** Replace each node of size $2^{O(k)}$ by a tree decomposition of width $O(k)$



Conclusion

- Dynamic treewidth in $2^{\mathcal{O}(k)} \log n$ amortized update time

Conclusion

- Dynamic treewidth in $2^{\mathcal{O}(k)} \log n$ amortized update time
 - ▶ Tree decomposition of width at most $9 \cdot \text{tw}(G) + 8$ of dynamic graph of treewidth $\text{tw}(G) \leq k$
 - ▶ Can also maintain dynamic programming schemes on the tree decomposition

Conclusion

- Dynamic treewidth in $2^{\mathcal{O}(k)} \log n$ amortized update time
 - ▶ Tree decomposition of width at most $9 \cdot \text{tw}(G) + 8$ of dynamic graph of treewidth $\text{tw}(G) \leq k$
 - ▶ Can also maintain dynamic programming schemes on the tree decomposition
- Open problems:

Conclusion

- Dynamic treewidth in $2^{\mathcal{O}(k)} \log n$ amortized update time
 - ▶ Tree decomposition of width at most $9 \cdot \text{tw}(G) + 8$ of dynamic graph of treewidth $\text{tw}(G) \leq k$
 - ▶ Can also maintain dynamic programming schemes on the tree decomposition
- Open problems:
 - ▶ From amortized to worst-case?
 - ▶ Can we rule out $f(k) + \mathcal{O}(\log n)$ update time?
 - ▶ Improve approximation ratio (3 seems to be a lower bound)

Conclusion

- Dynamic treewidth in $2^{\mathcal{O}(k)} \log n$ amortized update time
 - ▶ Tree decomposition of width at most $9 \cdot \text{tw}(G) + 8$ of dynamic graph of treewidth $\text{tw}(G) \leq k$
 - ▶ Can also maintain dynamic programming schemes on the tree decomposition
- Open problems:
 - ▶ From amortized to worst-case?
 - ▶ Can we rule out $f(k) + \mathcal{O}(\log n)$ update time?
 - ▶ Improve approximation ratio (3 seems to be a lower bound)

Thank you!