

# How Graph Structure Makes Hard Problems Tractable

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UNIVERSITY OF  
COPENHAGEN

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Aalto University

CS Special Seminar

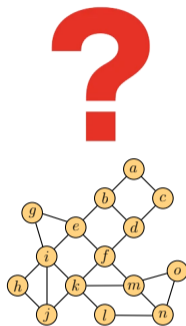
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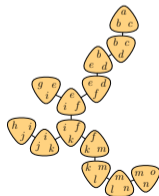
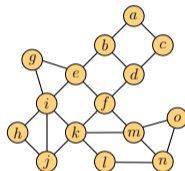
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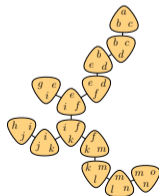
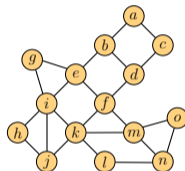


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1. Drawing the line between easy and hard instances using graph-theoretic methods
2. Designing algorithms to discover the graph-theoretic structure that can be exploited



⇒ Background and motivation

– My contributions

– Future research

## Example: Constraint Satisfaction Problems (CSPs)

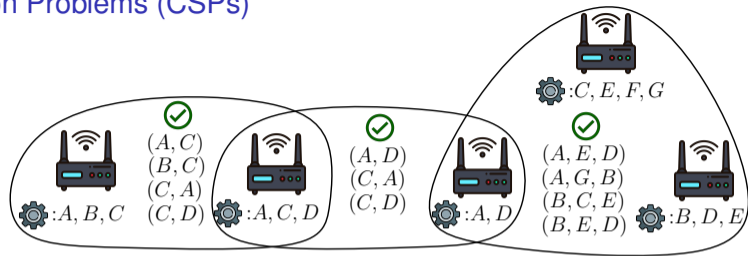
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### Wifi setting assignment:

Variables: Transmitters

Domains: Settings of transmitters

Constraints: Compatible settings



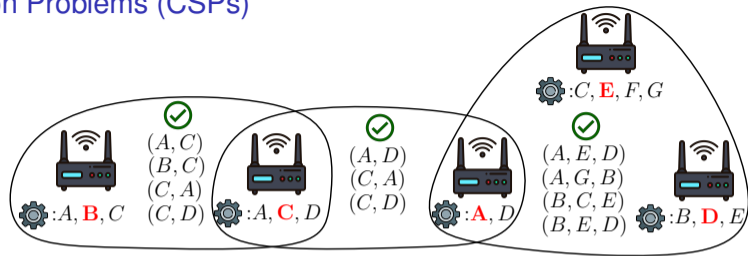
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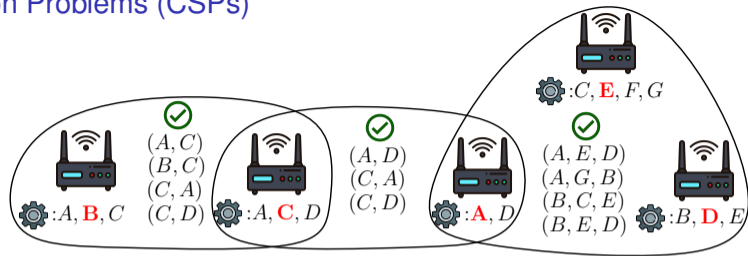
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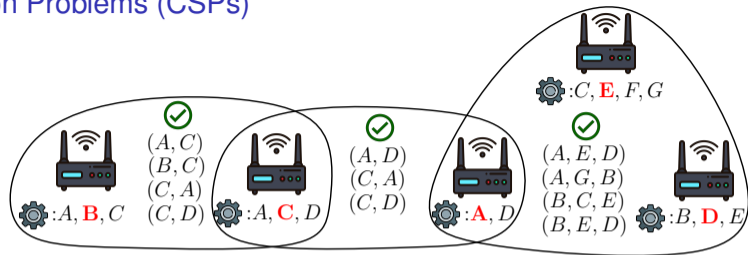
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Variables: Squares

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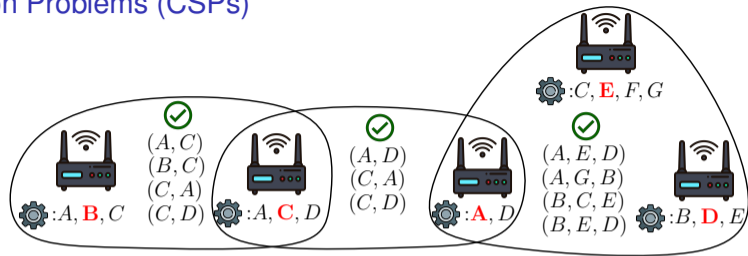
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### Join evaluation in databases:

Variables: Attributes (columns)

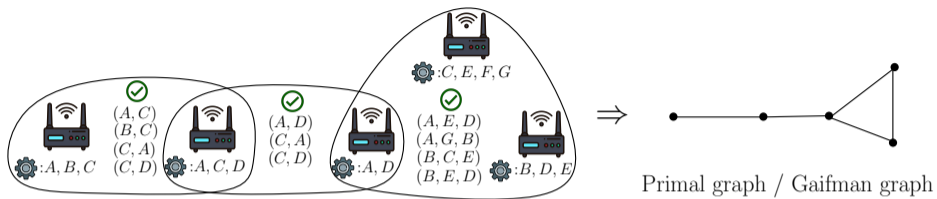
Domains: Values of attributes

Constraints: Tables of the database

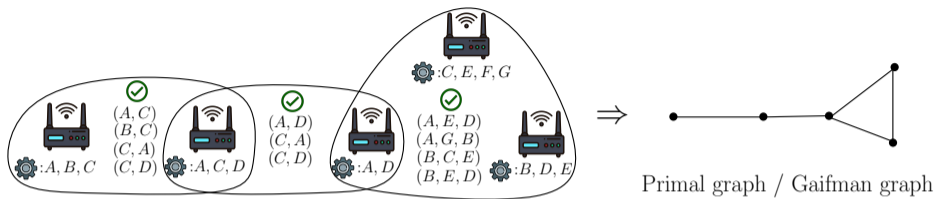


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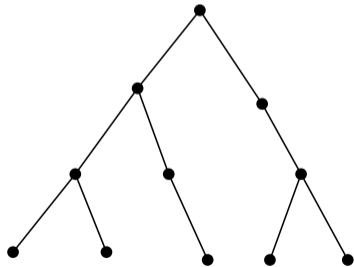
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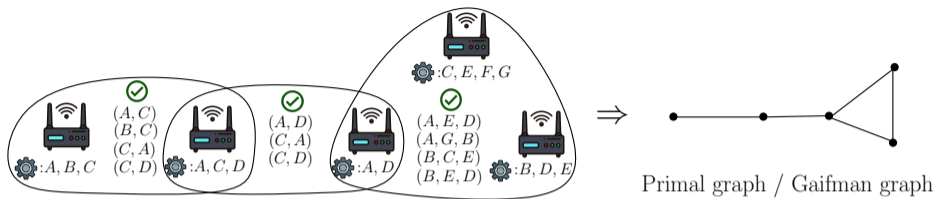
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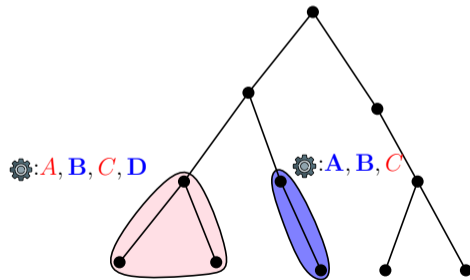


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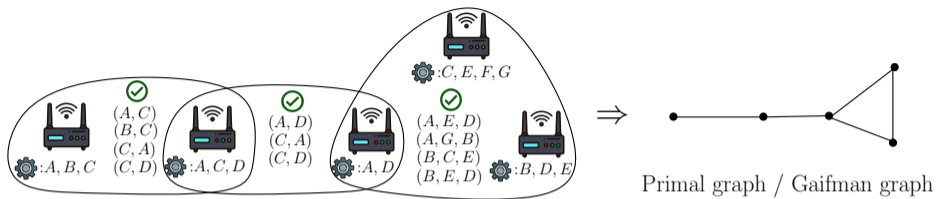


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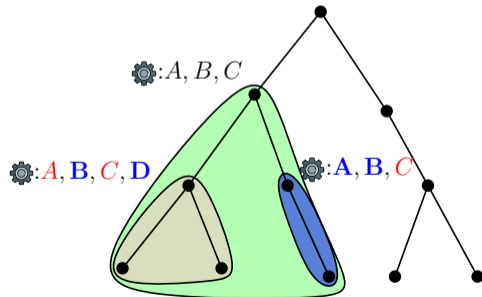


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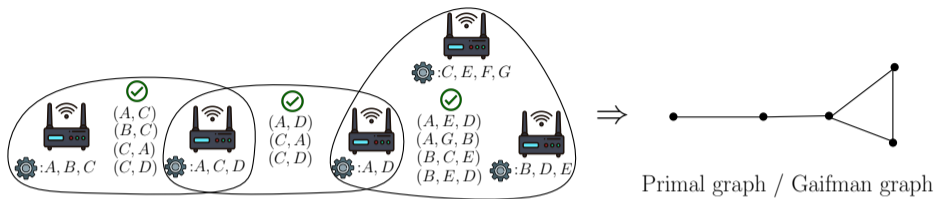


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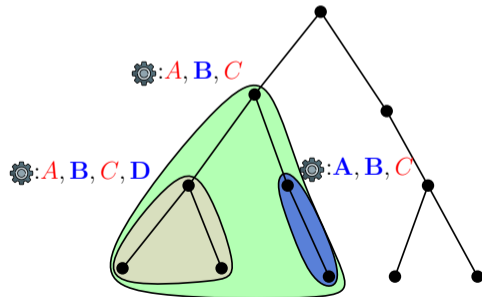
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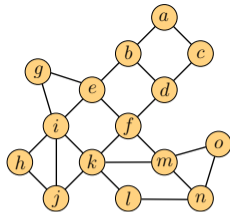
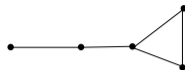
Bottom-up dynamic programming

⇒ Linear-time algorithm



## Treewidth

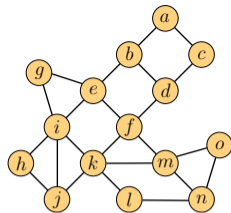
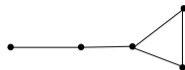
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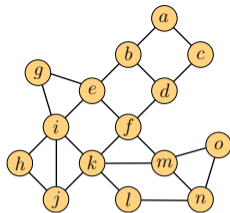
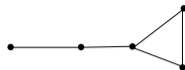


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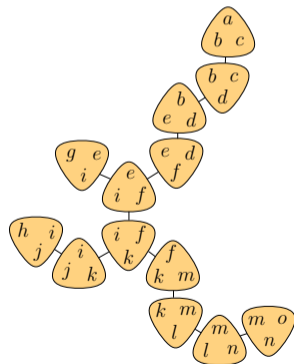
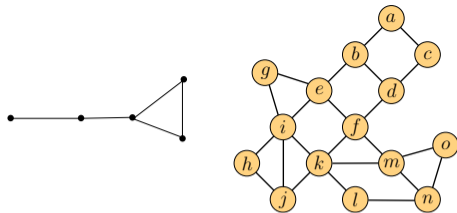
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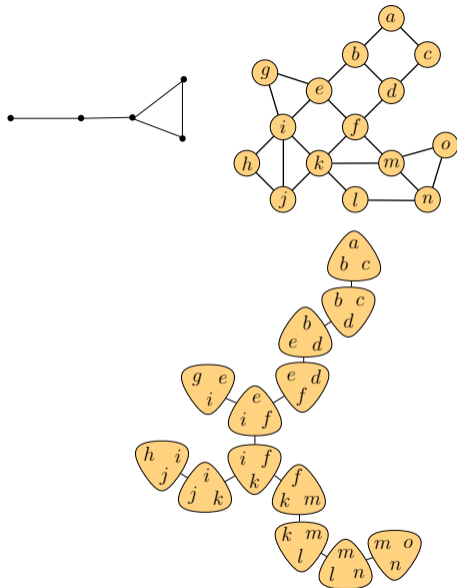
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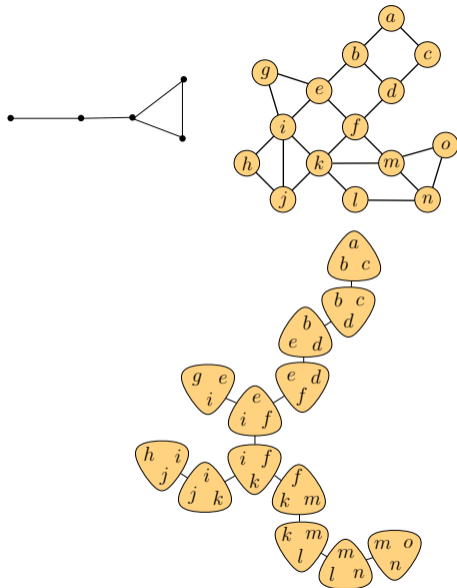
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Dynamic programming on tree decomposition to solve CSP

- ⇒ Running time  $\mathcal{O}(D^{k+1} \cdot n)$
- ▶  $n$ : Number of variables
  - ▶  $D$ : Domain size
  - ▶  $k$ : Treewidth



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- We can solve CSP in time  $\mathcal{O}(D^{k+1} \cdot n)$ , where
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[Marx, FOCS'07]

: No (under certain assumptions)

### Theorem (informal)

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Instance-optimal over the primal graphs

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Treewidth was (re-)invented by:

- [Bertele & Brioschi](#) for dynamic programming, 1972
- [Robertson & Seymour](#) for theory of graph minors, 1983
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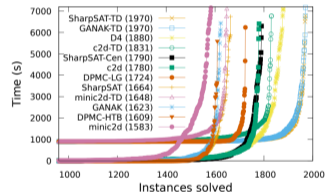
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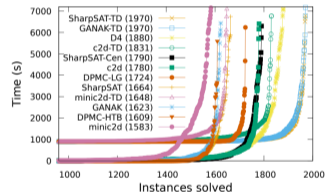
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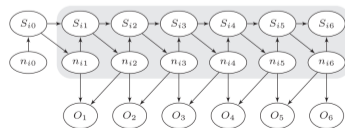
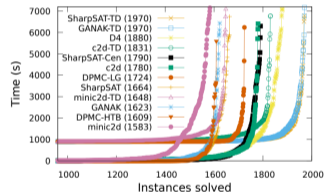
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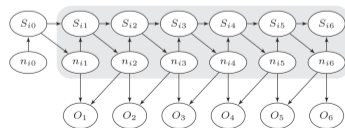
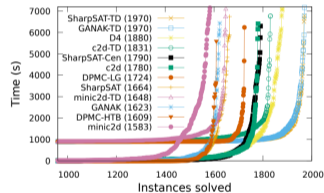
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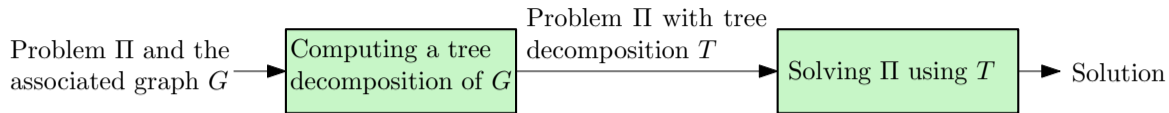
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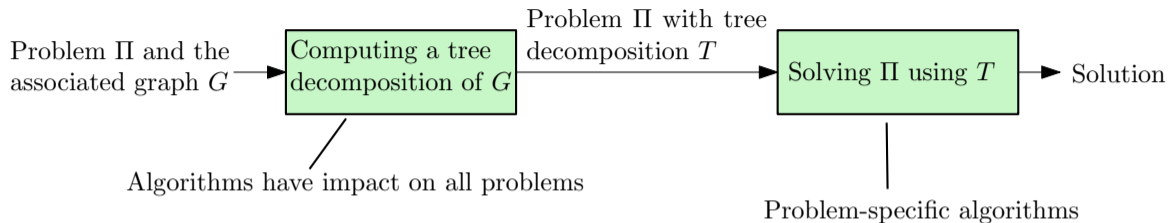
- #SAT (counting the number of solutions for SAT)
- Quantum computer simulation (tensor network contraction)
- Probabilistic inference (junction tree algorithm)
- Join evaluation in databases (fractional hypertreewidth, submodular width)



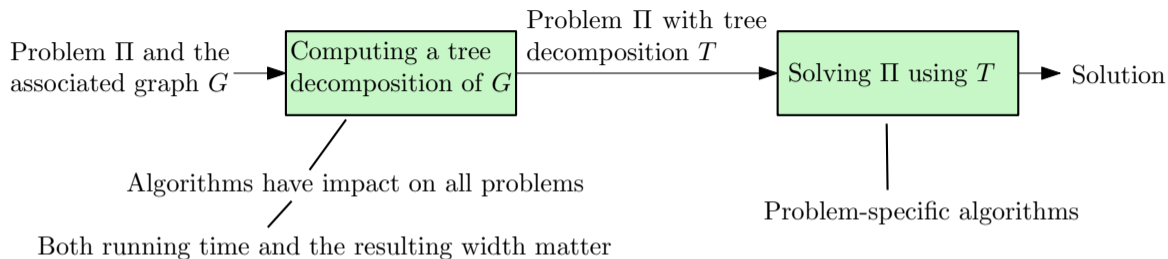
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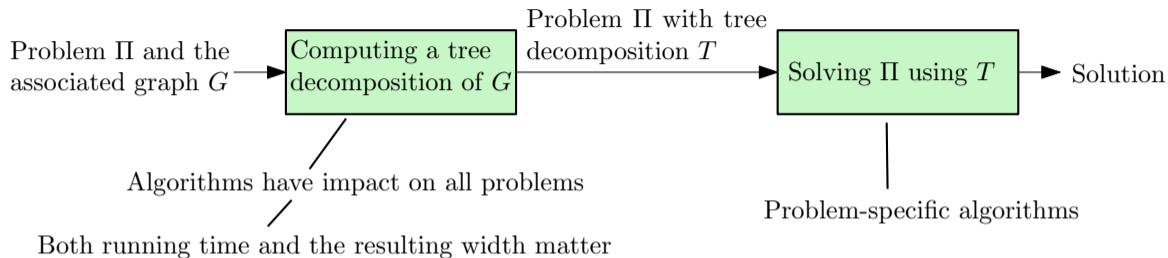
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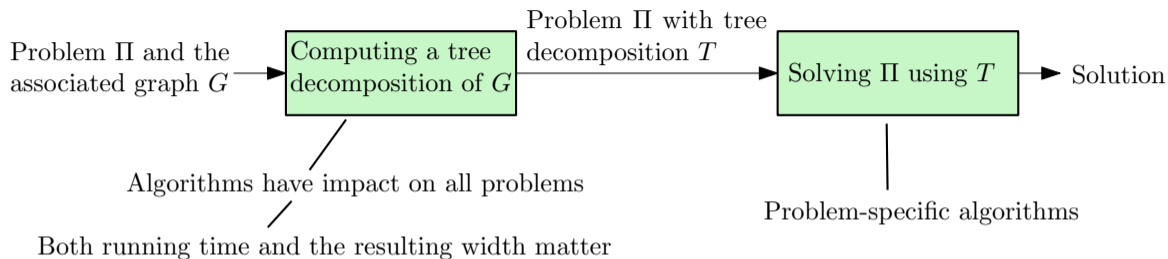


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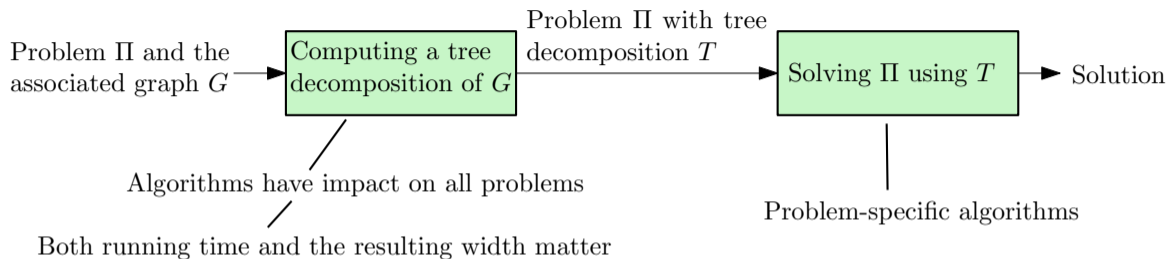
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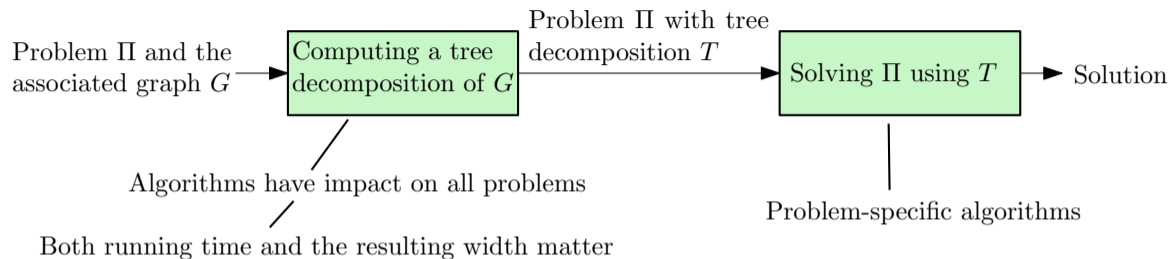
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- [Robertson & Seymour, 1987]: Treewidth can be 4-approximated in time  $\mathcal{O}(3^{3k} n^2)$

- Background and motivation

- ⇒ **My contributions**

- Future research

## Algorithms for Computing Treewidth

Ref.	Appx. ratio	Run. time
[RS'87]	4	$3^{3k} n^2$
[ACP'87]	exact	$n^{k+1}$
[RS'87]	exact	$f(k) \cdot n^2$
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- [Korhonen, FOCS'21]: New “local improvement” technique for approximating treewidth

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- [Korhonen, FOCS'21]: New “local improvement” technique for approximating treewidth
  - ▶ Improves approximation ratio below 3, breaking the RS-barrier (open problem asked by [BDDFLP'13])
  - ▶ Achieves running time  $2^{\mathcal{O}(k)} n$ , while simpler than previous such algorithms

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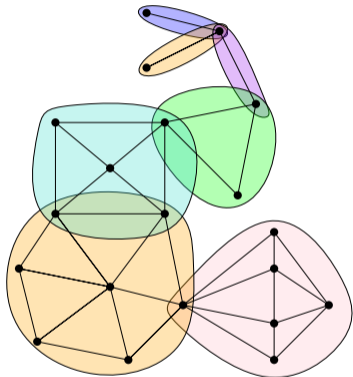
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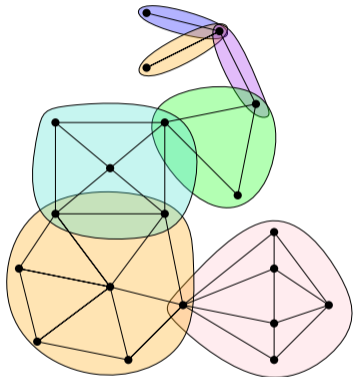
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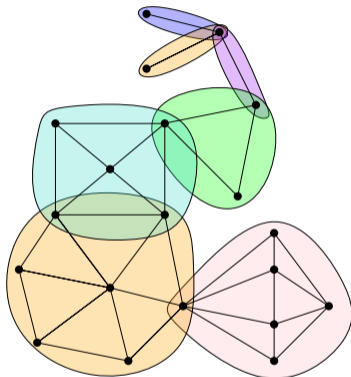
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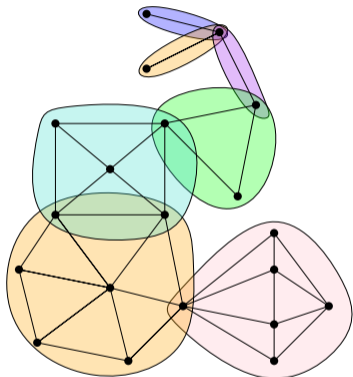
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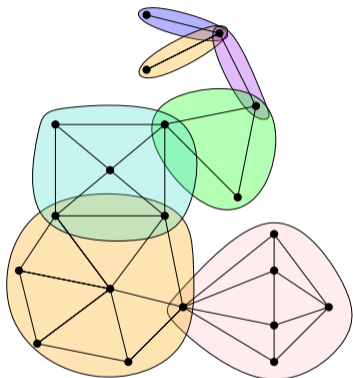
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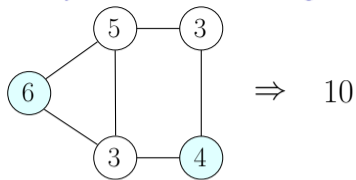
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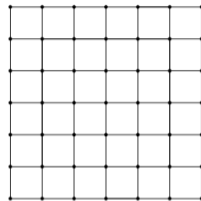
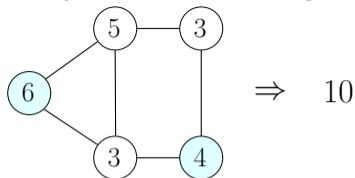


- Background and motivation
- My contributions
- ⇒ **Future research**

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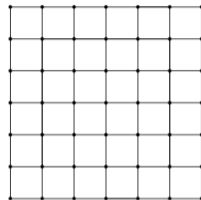
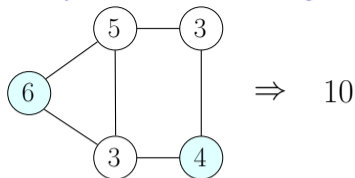


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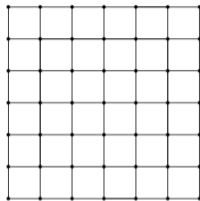
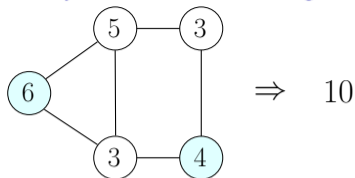
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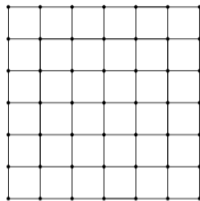
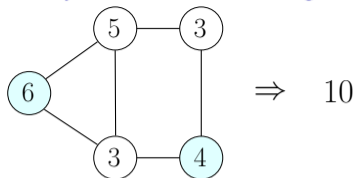
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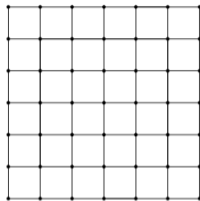
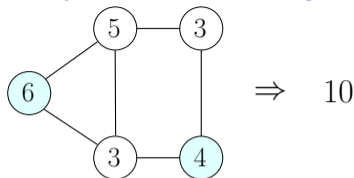
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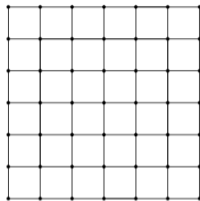
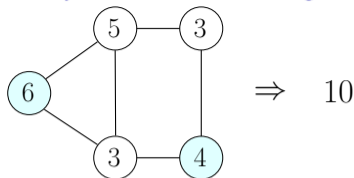
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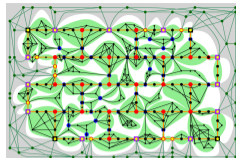
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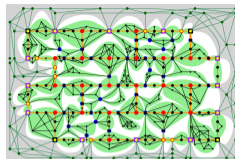
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High treewidth  $\approx$  can embed planar graphs as minors  
[Robertson & Seymour '86]

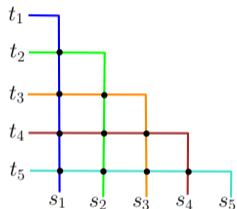


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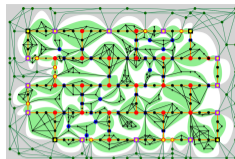


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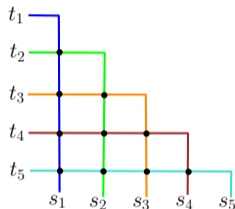


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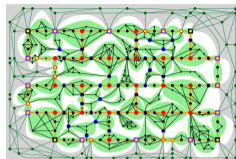
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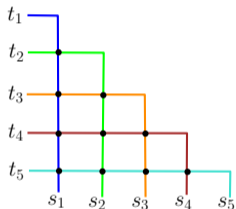
**Goal:** Framework for instance-optimality results by techniques of Chekuri & Chuzhoy

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[Chekuri & Chuzhoy '16]



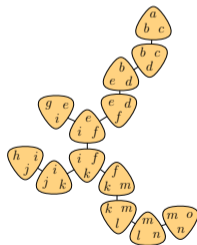
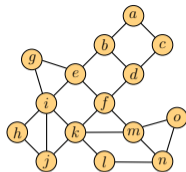
**Goal:** Framework for instance-optimality results by techniques of Chekuri & Chuzhoy

**Concrete settings:**

- Grohe-Schwentick-Segoufin-Marx CSP result for bounded-domain CSPs?
- SAT?
- Monadic Second-Order logic?

## Conclusion

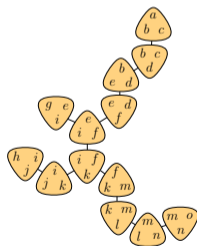
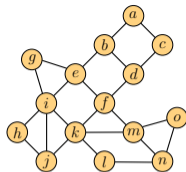
Structure matters for solving algorithmic problems



## Conclusion

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Two connected themes of research:

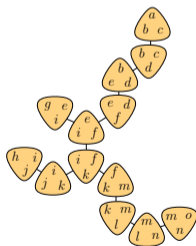
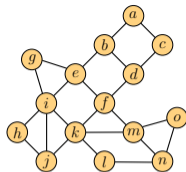


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1. Drawing the line between easy and hard instances using graph-theoretic methods

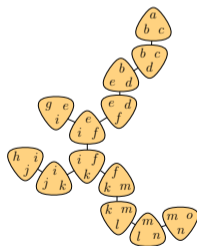
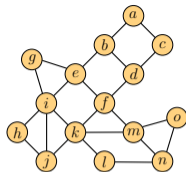


## Conclusion

### Structure matters for solving algorithmic problems

Two connected themes of research:

1. Drawing the line between easy and hard instances using graph-theoretic methods
  - ▶ **Contribution/future:** Understanding dense structure via MWIS
  - ▶ **Future:** Instance-optimality results via constant-congestion minors



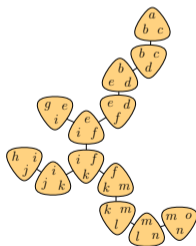
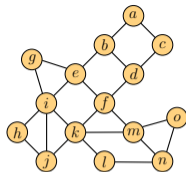


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1. Drawing the line between easy and hard instances using graph-theoretic methods
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  - ▶ **Contribution:** Faster algorithms for computing treewidth
  - ▶ **Contribution:** Linear-time algorithms for  $k$ -connected components
  - ▶ **Future:**  $k^{O(1)}n$  time algorithms for these problems

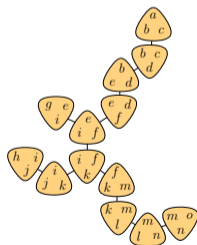
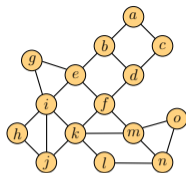


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Thank you!