

Tutorial: New methods in FPT algorithms for treewidth

Tuukka Korhonen



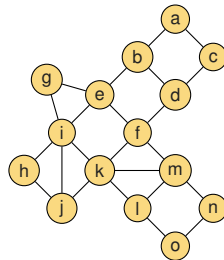
UNIVERSITY OF BERGEN

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7 September 2023

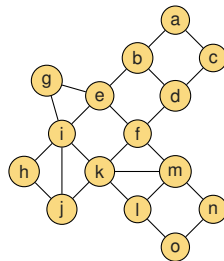
Treewidth

- Measures how close a graph is to a tree



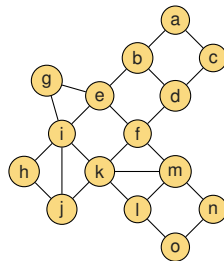
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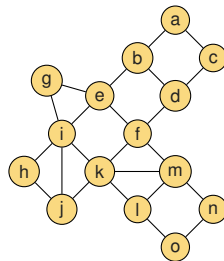
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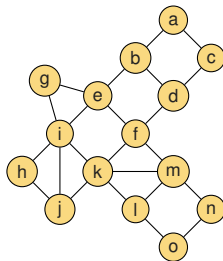
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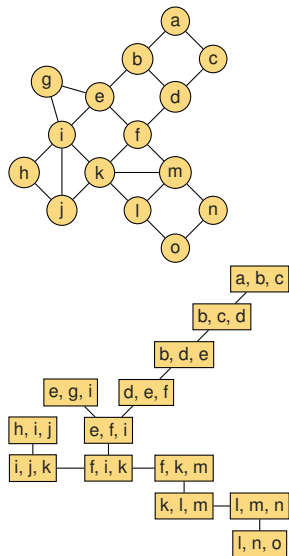
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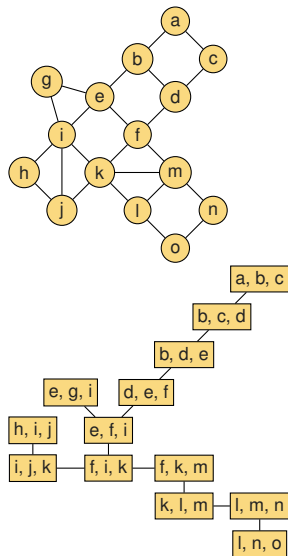
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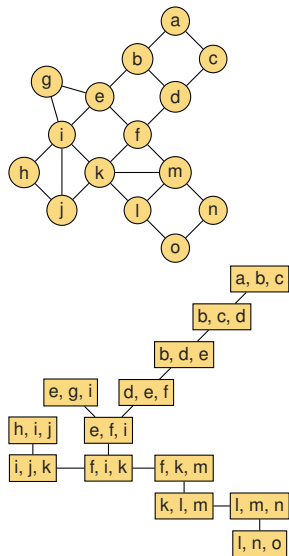
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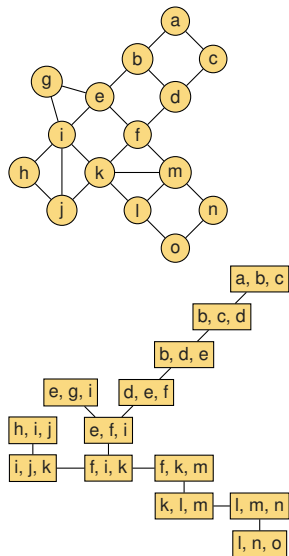
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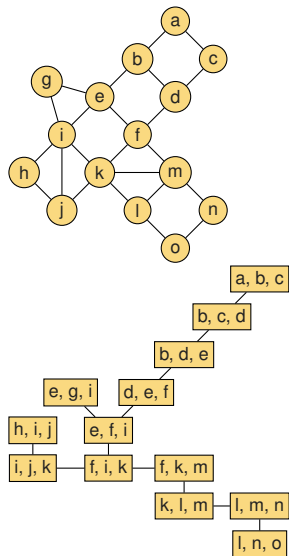
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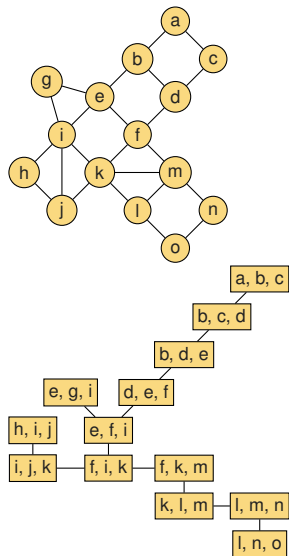
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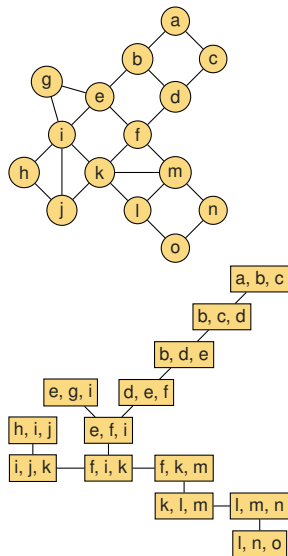
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[Robertson & Seymour '84, Arnborg & Proskurowski '89,
Bertele & Brioschi '72, Halin '76]

Computing treewidth

Computing treewidth: Classical results

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Theorem (Robertson & Seymour, Graph minors XIII, '86)

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Many more: [ACP'87, MT'91, Lagergren'96, Reed'92, Amir'10, FHL'08, FTV'15, FLS'18, BF'21, BF'22]

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There is a data structure for maintaining a tree decomposition of width $\mathcal{O}(k)$ for a fully dynamic graph of treewidth $\leq k$ with amortized update time $f(k) \cdot n^{o(1)}$.

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(first non-trivial algorithm in this setting for $k \geq 3$)

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1. Local improvement for FPT **exact** treewidth (joint work with Daniel Lokshtanov)

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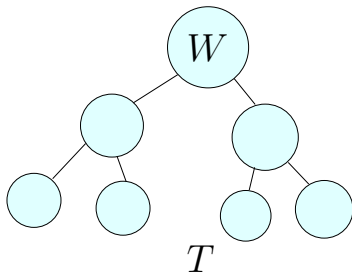
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Local improvement for FPT **exact** treewidth

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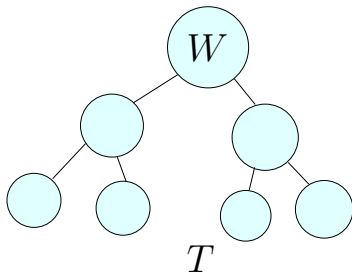
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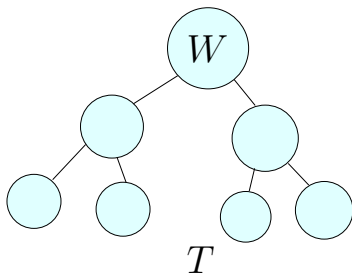


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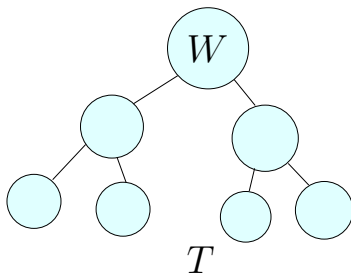


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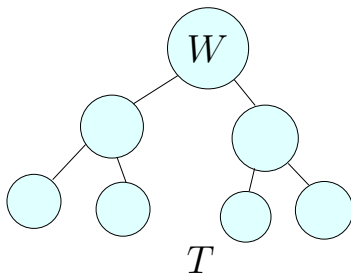
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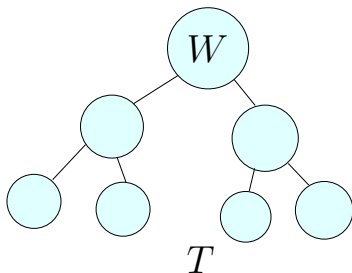
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(by [Bodlaender'93] we can assume to start with a decomposition of width $\mathcal{O}(\text{tw}(G))$)



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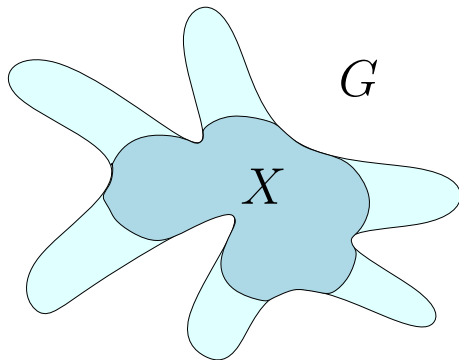
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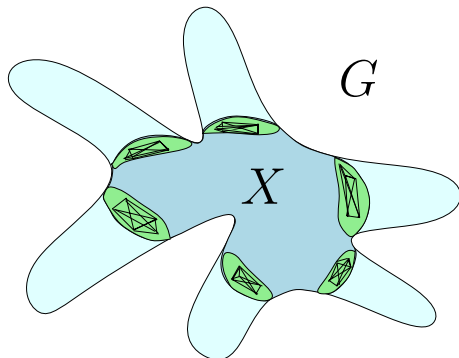
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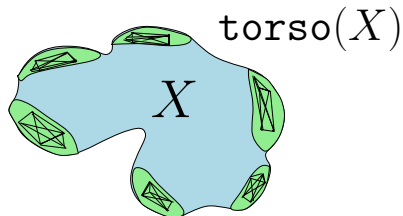
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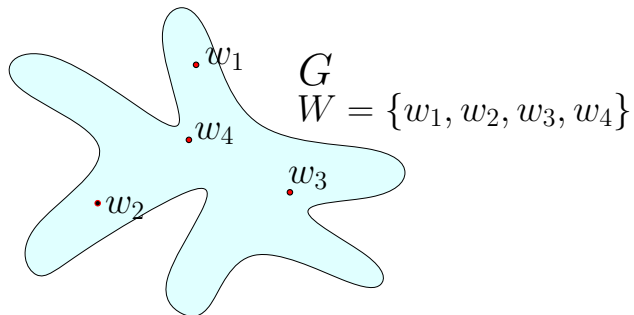
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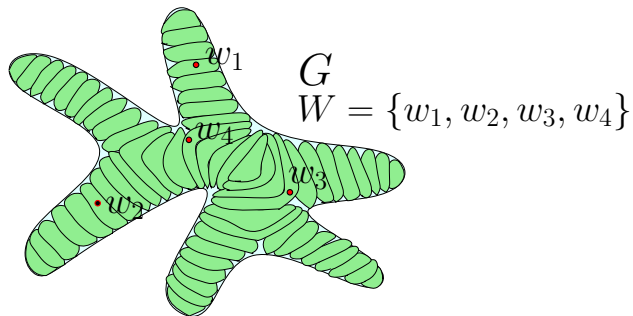
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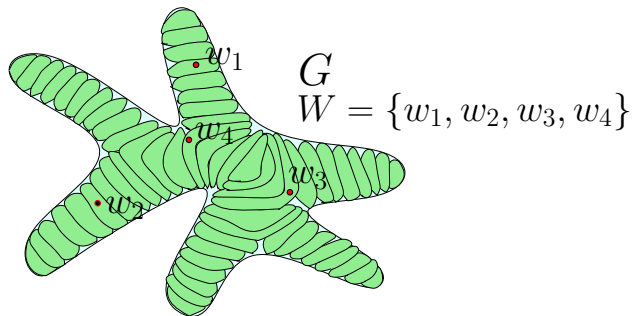
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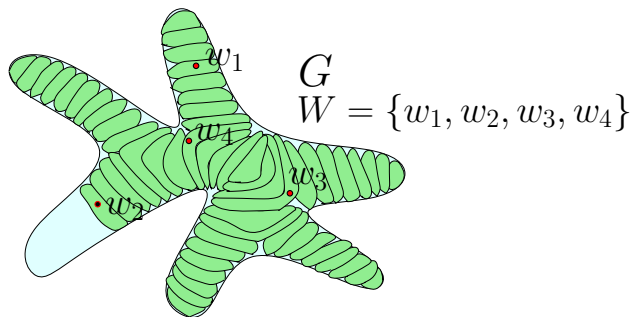
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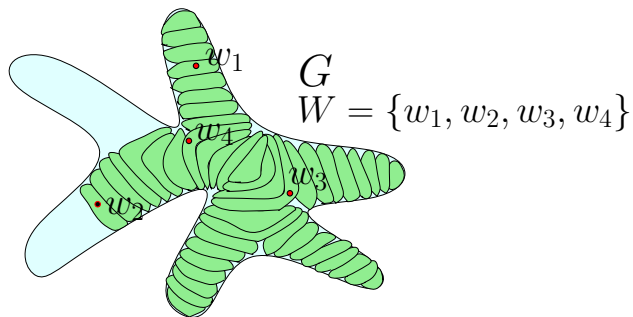
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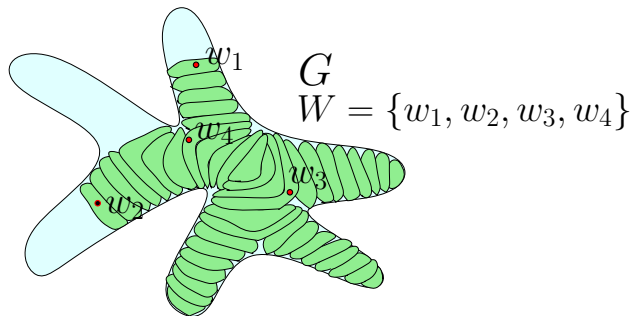
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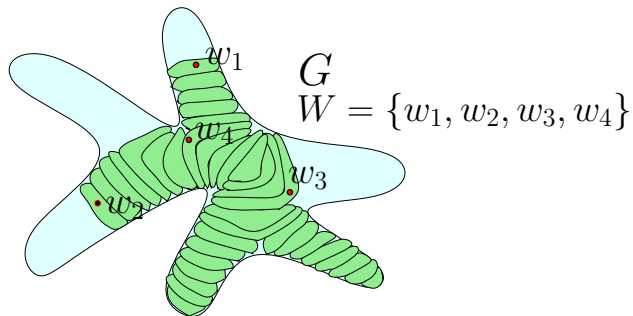
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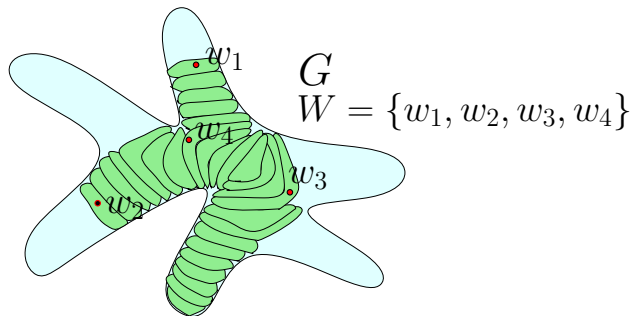
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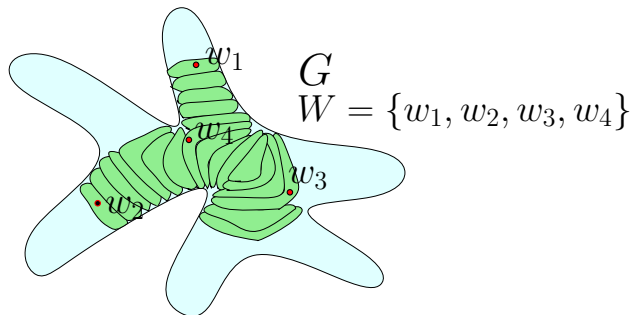
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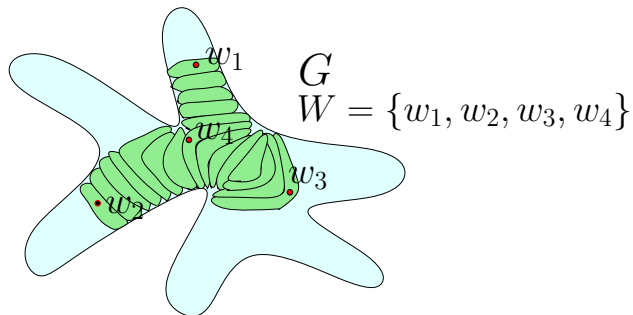
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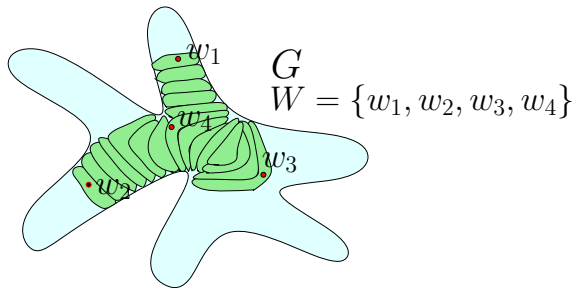
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Big-leaf formulation:



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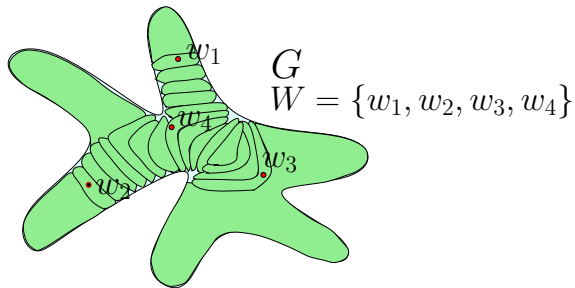
SUBSET TREewidth

Want to find:

- a set X with $W \subseteq X \subseteq V(G)$, and
- a tree decomposition of $\text{torso}(X)$ of width $\leq |W| - 2$

Big-leaf formulation:

- Find a tree decomposition of G whose internal bags have size $< |W|$ and cover W , but leaf bags can be arbitrarily large



Improving a tree decomposition

Let W be a largest bag of T

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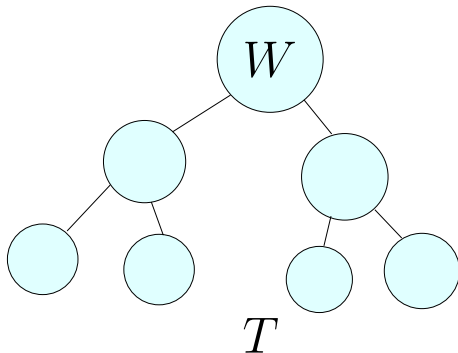
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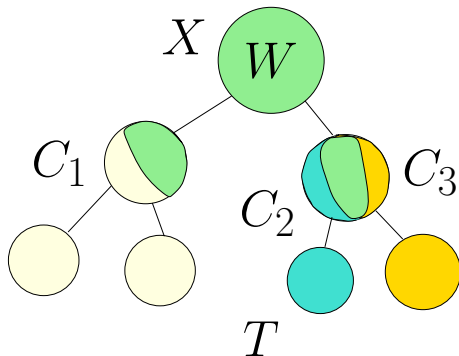
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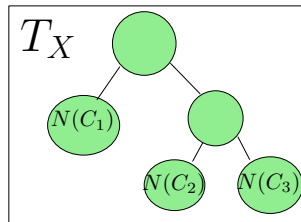
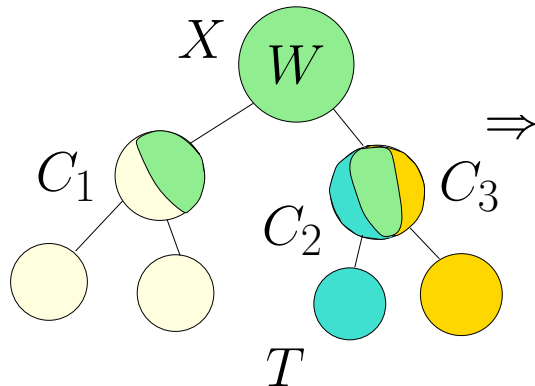
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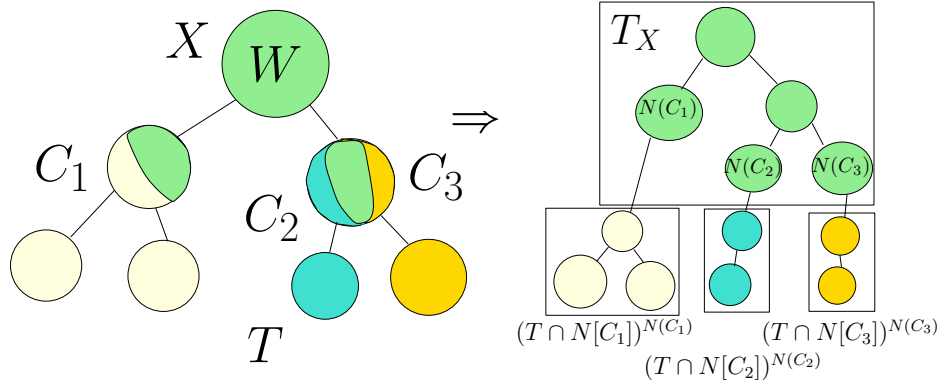
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Constructing $(T \cap N[C_i])^{N(C_i)}$

Goal: For each component C_i of $G \setminus X$, construct a tree decomposition of $G[N[C_i]]$ so that $N(C_i)$ is in the root

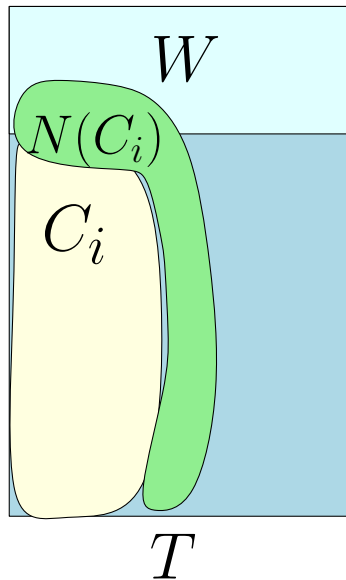
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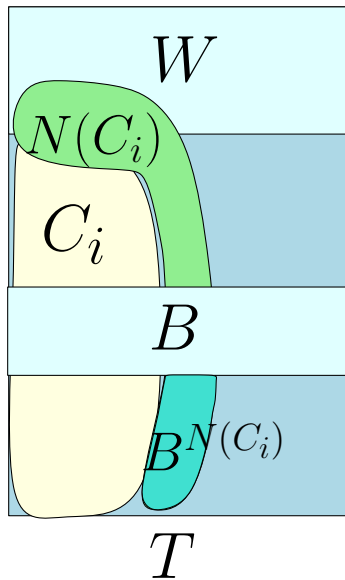


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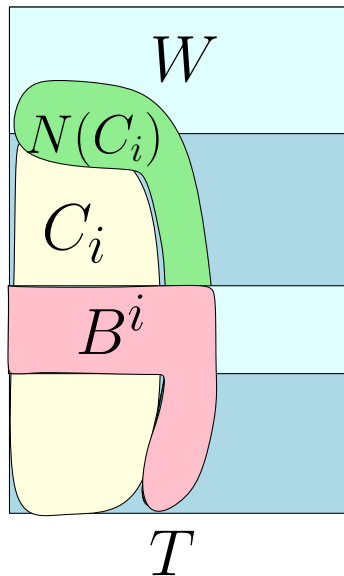


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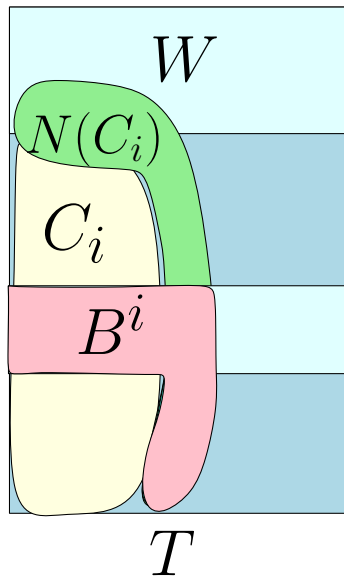
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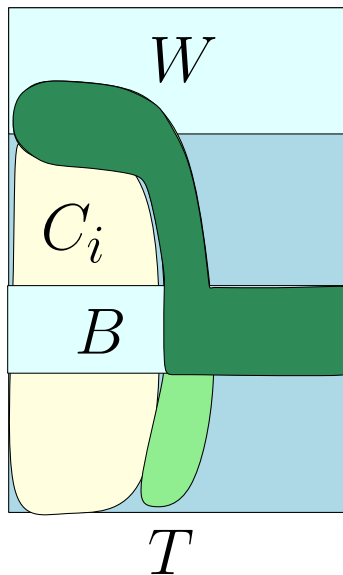
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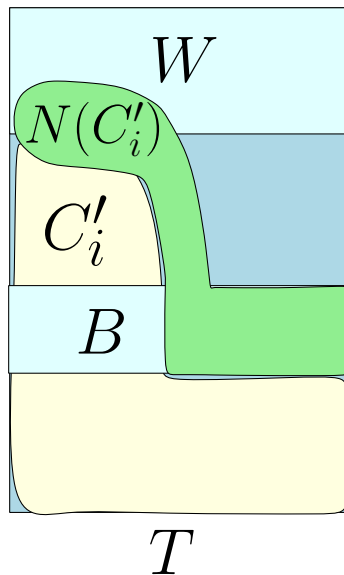
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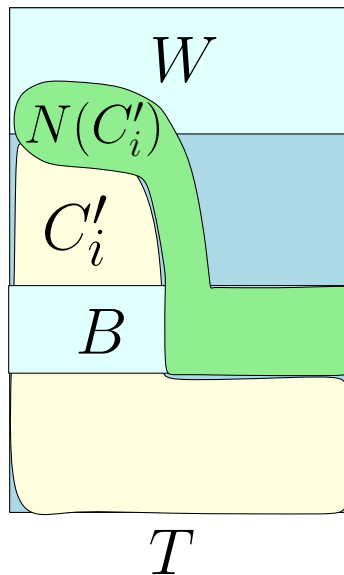
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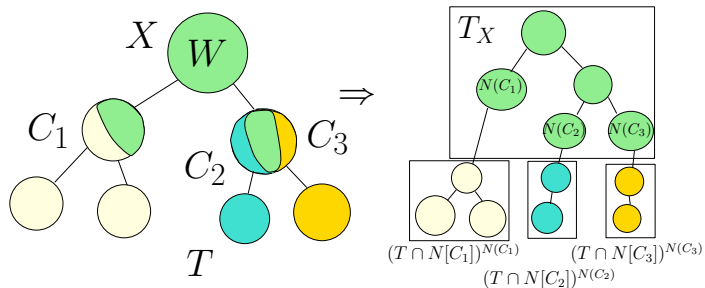
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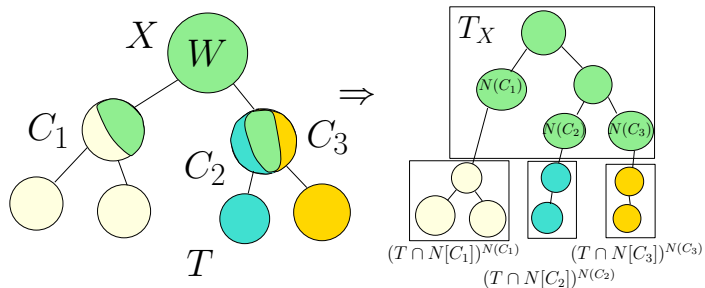


Result



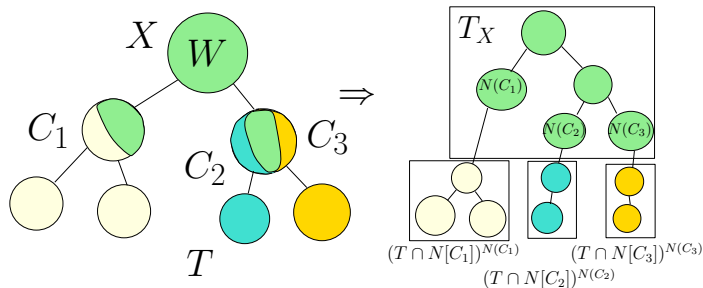
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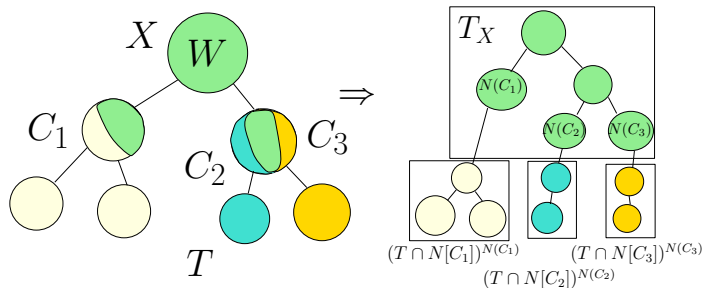
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- Proof idea generalization of proofs of existence of lean tree decompositions [Thomas '90, Bellenbaum & Diestel '02]

Subset treewidth for exact FPT algorithms

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SUBSET TREewidth

Input: Graph G , integer k , set of vertices $W \subseteq V(G)$ with $|W| = k + 2$

Output: Set $X \subseteq V(G)$ with $W \subseteq X$ and tree decomposition of $\text{torso}(X)$ of width $\leq k$ or that the treewidth of G is $> k$

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Theorem

If there is an $f(k) \cdot n^{O(1)}$ time algorithm for subset treewidth, then there is an $f(k) \cdot n^{O(1)}$ time algorithm for treewidth with the same function f .

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$2^{\mathcal{O}(k^2)} n^2$ time algorithm for subset treewidth $\rightarrow 2^{\mathcal{O}(k^2)} n^4$ time algorithm for treewidth

How to solve subset treewidth?

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Techniques:

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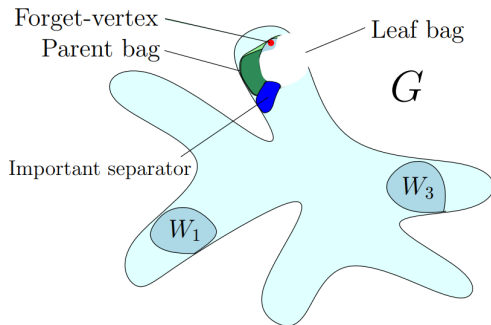
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Local improvement in dynamic treewidth

joint work with Konrad Majewski, Wojciech Nadara, Michał Pilipczuk & Marek Sokołowski

Local improvement in dynamic treewidth

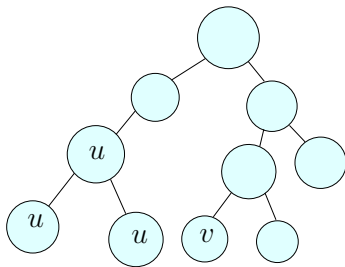
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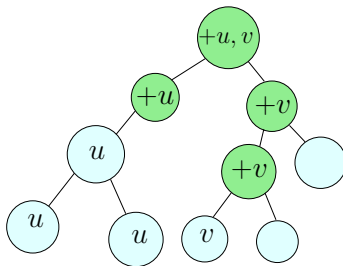
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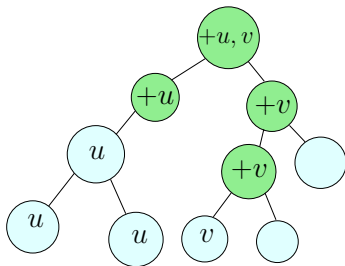
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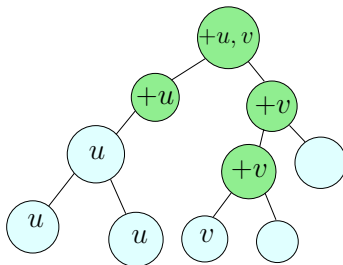
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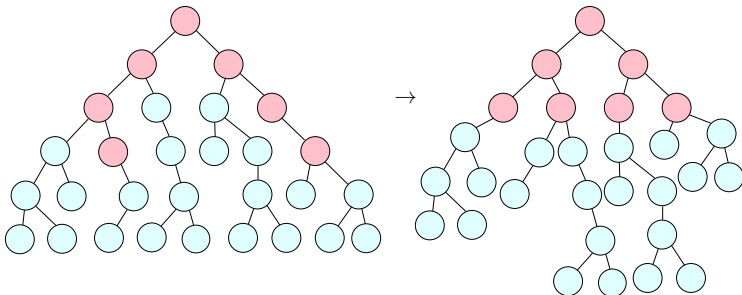
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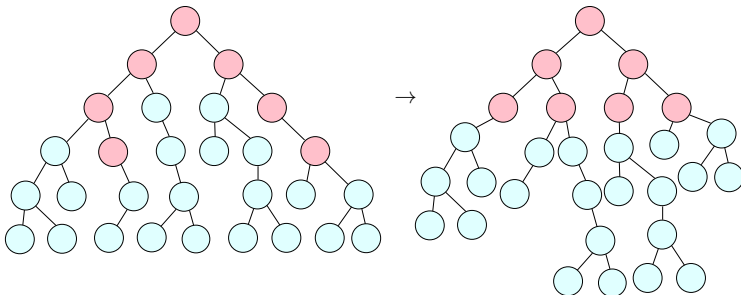
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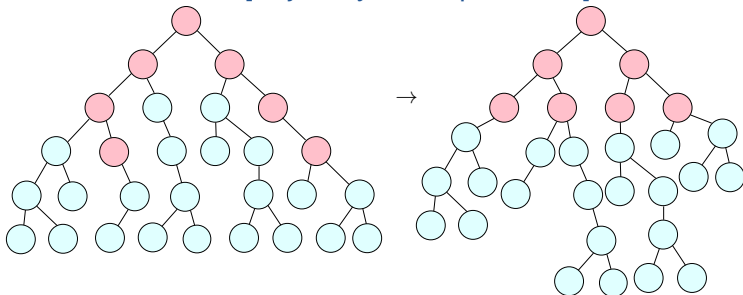
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- Builds on subset treewidth, log-depth decompositions [Bodlaender & Hagerup '98], and the “dealternation lemma” [Bojańczyk & Pilipczuk '22]



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